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UNI-LIFT[®] Section Index

www.uniliftjacks.com

Visit the UNI-LIFT Website to find:

- New product information
- Product manuals (instruction and repair part sheets)
- Integrated Solutions applications from around the world
- Ordering instructions to request product catalogs

CONTACT INFORMATION:

Customer Service: (630) 408-9349 Toll Free: (888) 984-1924

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sales@uniliftjacks.com





UNI-LIFT® Screw Jack Overview

UNI-LIFT[®]

UNI-LIFT offers a complete range of high force tools and equipment for all industrial applications, with local availability and after sale service.

The UNI-LIFT product line is an engineered solution offering precision control in a mechanical package. Design principals integrate a power screw which converts rotary motion to linear movement. Configurations in either standard or custom designs cover a wide range of applications and use.

UNI-LIFT Screw Jacks provide force up to 250 tons, travel lengths up to 20 feet and speeds up to 175 in/min. Each Screw Jack utilizes a high-strength rolled screw and hardened gear nut to provide maximum durability. The housings are constructed with aluminum alloy or ductile iron material coupled with corrosion-resistant plating to withstand the most demanding and rigorous environments.

In addition, UNI-LIFT offers a comprehensive range of accessories to complete your system arrangement for added flexibility.





UNI-LIFT[®] Solutions in Action



Engineers utilized two (2) UNI-LIFT 100-ton Screw Jacks with 15' of travel to raise and lower the ramp on each ferry dock along the Mississippi River, USA. The Department of Transportation engineers needed a way of lifting and lowering ramps during high and low tide conditions, while holding up to the harsh environmental conditions of the Gulf Coast.







UNI-LIFT Screw Jacks are used extensively in a variety of material handling applications. Whether used to position conveyer belts, place tension on overhead beams or to move heavyduty equipment, UNI-LIFT Screw Jacks are the ideal solution for many jacking, tensioning, and positioning applications. Whether you have one or multiple lifting points, UNI-LIFT Screw Jacks are the perfect solution for many different OEM material handling and motion-control applications.



UNI-LIFT[®] 3

UNI-LIFT[®] Product Overview

UNI-LIFT®

Model Type

- M-Series Machine Screw
- B-Series Ball Screw

Mounting Styles

- Inverted
- Upright
- Double Clevis

Screw Configurations

- Rotating
- Translating
- Keyed
- Anti-Backlash (applicable models)

Gear Ratios (Ratios vary with tonnage)

- Low
- Medium
- High

End Configurations

- Threaded
- Plain
- Clevis
- Top Plate





Product Overview

Drive Options

- Couplers
- Motors
- Motor Adaptors
- Worm Gear Reducers
- Mitre Gear Boxes
- Shafting
- Hand Wheels

Control Options

- Limit Switches
- Control Boxes / Encoders
- Transducers
- Digital Displays

Protective Options

- Boots
- Stop Nuts



Innonnth

UNI-LIFT[®] System Design

UNI-LIFT®

Key Points to Consider When Properly Sizing an Screw Jack

- Total system load
- Application loading conditions
- Operating intervals of the screw jack
- Linear velocity requirements
- Ambient temperature

- Environmental conditions
- Mounting position requirements
- Load screw configuration
- Screw length requirements
- End mounting requirements
- System components needed

Refer to technical specifications on pages 14 & 36.



Total Load Requirements

UNI-LIFT Screw Jacks can be used individually or in combination with each other to move a load.

- When a single screw jack is used, the maximum load is the highest force value the screw jack will have to sustain in a particular application.
- When more than one screw jack is used, the load can be evenly distributed or unbalanced where one or more screw jacks in the system are subjected to a higher force in the system.
- The maximum load in an unbalanced system is equal to the highest force applied to a single screw jack in the system. In the case of an unbalanced load, size the screw jack based on the maximum force applied to a single screw jack.



Compression



Application Loading Conditions

Loading conditions are factors that can affect the load screw during the operation. The orientation of the screw jack to the load can cause the load screw to be axially loaded in compression or tension. If the load screw will see both compression and tension loads, the use of the anti-backlash design is recommended. *Refer to page 72.*

- Guided loads describe a loading condition where proper alignment between the screw jack and the load is maintained by external guiding in the structure. With longer columns guided loads allow you to double your load screw length for a given load.
- Unguided loads describe a loading condition where the screw jacks must rely on the load screw to maintain alignment of the system. Side loads are not recommended in an unguided system.

Refer to the Technical Information Section 71 & 76 for Column Buckle information to properly size your screw jack.



System Design

Usage Requirements

• Operating Cycle Requirements To determine the type and size of the screw jack, calculate the required duty and operating cycles.

Refer to the Technical Information Section 70 & 75 for Duty Cycle information to properly size your screw jack.

• Linear Velocity Requirements Linear velocity is the speed that the screw jack moves the load based on the output speed of the motor. Turns Per Inch (TPI) is the number of rotations of the screw jack's input shaft required for one-inch of travel. Screw Jacks are available in two to three different gear ratios.

Operating Temperature

To determine the duty cycle limit you will need the maximum temperature the screw jack will be exposed to. For severe conditions, UNI-LIFT offers seal and grease options capable of operating in temperatures from -40° F to 400° F.

For detailed information on Safety, Installation and Maintenance refer to page 80 of the Technical Information Section . • Environmental Conditions The screw jack may require a boot to protect the load screw. Boots are used when the load screw may be exposed to contamination, corrosive environments, where an exposed screw is viewed as a hazard or where it is critical to ensure lubrication is retained

within the screw jack to meet cleanliness requirements.

Refer to Accessory page 62 for detailed information on Boot Sizing.





Determine Which Screw Jack Best Suits the Application

- M-Series Machine Screw Jack General applications where the load screw uses a precision rolled acme, self locking screw thread that requires no cribbing to hold load into position.
- **B-Series Ball Screw Jack** Used in high cycle applications, the load screw uses a precision rolled ball screw. A ball screw is 90% efficient, offering a smoother, faster operation. A mechanical break is required to hold position.

Refer to M- and B-Series Overview pages 12 and 36 for detailed information on screw jack models.



B Series

UNI-LIFT[®] System Design

UNI-LIFT®

End Configurations

• Threaded End (1)

The end of the load screw is machined to include a standard unified V-thread form strong enough to sustain the load capacity of the screw jack. This option can be used to attach customer supplied mounting configurations.

• Plain End (2)

The end of the load screw is machined to provide a smooth, unthreaded portion suitable for engaging pillow blocks or other bearing supports. Bearing supports are highly recommended when long load screws are used. This option is only available with the Rotating design.

• Clevis End (3)

The end of the load screw features a cross hole for mounting with a pinned connection. This option is used in applications that require a pivoting mount.

• Top Plate (4)

The end of the load screw is adapted with a flange to provide mounting to surfaces perpendicular to the load screw. This option will easily adapt to mounting structures.



Determine The Mounting Style

- Inverted Configuration The load screw protrudes from the same side as the machined mounting face on the housing.
- Upright Configuration The load screw protrudes from side opposite the machined mounting face on the housing.
- **Double Clevis Configuration** The mounting points for the housing and the screw are clevis and pin type. (Illustration not shown.)

Determine Load Screw Configuration

Translating Design The load screw is threaded into the driven gear. Rotation of the input shaft turns the driven gear which moves the load screw in and out of housing.

•

- Rotating Design The load screw is pinned to the driven gear. Rotation of the input shaft turns the driven gear which rotates the load screw. An auxiliary nut travels the exposed length of the load screw.
- Keyed Screw Design
 A key prevents the load screw
 rotation. Due to the inefficiency of
 this design, they are down rated to
 25% of the load rated capacity.
 (Illustration not shown.)
- Anti-Backlash Design
 An adjustable nut on the load
 screw eliminates axial endplay.
 (Illustration not shown.)
 Refer to page 72 for details.



Upright

Inverted



System Design

Determine The Extended Screw Length (ESL)

The length of screw that is needed to achieve the required movement, and allow for boot closed heights, traveling nuts, stop nuts and the thickness of the supporting structure between the screw jack and the load.

Refer to the Technical Information Section 71 & 76 for more information on ESL.



System Arrangement

Screw Jacks can be configured in multiple system arrangements to allow synchronized lifting. Even when the loads are unequally distributed, the system can lift uniformly. UNI-LIFT offers a complete line of power transmission equipment that can be used to set up your system.

equipment (reducers, mitre gear

ratings greater than the torque

Size shafting for system starting

boxes, couplings, etc.) with

torque to be transmitted.

to be transmitted.

- Determine the system arrangement that best fits the application. Calculate the required torque and horsepower requirements for the system.
- Select a motor with a power rating greater than the horse power requirement and with starting and running torque capability greater than calculated torque requirements.
- Select system torque transmission

Refer to the Technical Information Section for more information on Motor Sizing and





UNI-LIFT[®] System Overview

UNI-LIFT®

UNI-LIFT understands that no two projects are alike; therefore, we offer specialized engineering and design expertise to complete your system integration. Whether you are driving a single screw jack or a multiple screw jack system, our comprehensive range of control technologies and accessories brings your system together. UNI-LIFT Application Engineers will deliver the precise technical information and support to specify screw jack sizing, motor sizing, controls, reducers, mitre boxes, couplings, shafting and pillow blocks to accommodate any system arrangement.

UNI-LIFT's extensive manufacturing capabilities provides a single source for all of your equipment requirements.

Sample system arrangements are shown to help generate ideas. Additional information is included in the Technical Information Section starting on page 64 or contact UNI-LIFT for assistance.



UNI-LIFT Screw Jacks were the ideal choice for adjusting complex scaffolding required in aircraft maintenance. Their precision movement allowed safe, efficient control and positioning.



System Overview

System Arrangement Reference Numbers

- ① UNI-LIFT® Screw Jack
- ② Shafting
- ③ Motor Adaptor
- ④ Worm Gear Reducer
- 5 Motor
- 6 Coupler
- ⑦ Mitre Gear Box

▼ Single Point Screw Jack System



▼ Two Point Screw Jack System



▼ Four Point Screw Jack System



M-Series, Screw Jack Overview

UNI-LIFT[®]

UNI-LIFT Machine Screw Jacks offer precise positioning, uniform lifting speeds and capacity up to 250 tons. Standard model configurations include upright or inverted units with translating or rotating lifting screws. End configurations are available in top plate, plain, threaded or clevis ends.



Machine Screw Cutaway

Screw End Configurations

• Variety of end configurations are available including: threaded, clevis, plain and top plate.

High Strength Roll-Formed Threaded Load Screw

- Provide minimum friction for smooth operation and longer life
- Self-locking, highly accurate lead design to provide positive positioning
- Minimal axial backlash with Class 3G fit

Tapered Roller Bearings

- Preloaded for reduced assembly spring rate and high thrust loads
- Provides excellent support for side loading and horizontal applications
- Maintains exact gear alignment under separating and thrust forces
- Bearings sized for endurance and maximum loading conditions

High Strength Gearing

- Precision gears manufactured to American Gear Standards with close tolerances and minimal backlash
- Heat treated worm gear set provides greater efficiency, higher input speed and extended life

Rugged Housings

Robust aluminum alloy or ductile iron construction

Machine Screw Jacks



Contact UNI-LIFT!

Contact UNI-LIFT for advice and technical assistance in the layout of your ideal UNI-LIFT System.

CONTACT INFORMATION: Customer Service: (630) 408-9349 Toll Free: (888) 984-1924

sales@uniliftjacks.com



Technical Calculations

For Technical Calculations, such as torque and motor sizing please see our "Technical Information Section". Page: 64



Frequently Asked Questions To get answers to frequently asked questions please see our "Technical Information Section".

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Capacity (tons)	Series	Page				
Technical S	pecs.	14				
Ordering Ma	atrix	15				
.25	MA5	16				
.75	MA15	17				
1	MA20	18				
1	M1	19				
2	M2	20				
3	М3	21 🕨				
4	M4	22 🕨				
5	M5	23				
8	M8	24 🕨				
10	M10	25 🕨				
15	M15	26				
20	M20	27 🕨				
25	M25	28				
30	M30	29 🕨				
40	M40	30 ►				
50	M50	31 🕨				
75	M75	32 ►				
100	M100	33 🕨				

M-Series, Machine Screw Jacks

UNI-LIFT[®]

Shown: Machine Screw Jacks



- Precision Rolled Acme Thread allows positioning within thousandths of an inch
- Self Locking No cribbing required when screw jack is subjected to minimal vibration
- Hardened Gear Set allows higher efficiency and longer life
- Precision Gears allow synchronized lifting in multi-screw jack systems
- Rugged housings made of Cast Aluminum Alloy (MA models) or Ductile Iron to safely mount to a variety of structures



Configure Your M-Series Machine Screw Jack

If you cannot configure your standard M-Series Screw Jack using the Matrix, please contact UNI-LIFT for further assistance.

Customer Service: (630) 408-9349 Toll Free: (888) 984-1924 sales@uniliftjacks.com

<u>Capacity:</u> .25-250 ton

Maximum Travel: 232 inches

Maximum Speed: 129 in/min



System Accessories

UNI-LIFT[®] offers a large array of motors, drive components, and boots to meet any demanding project.

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Customized Solutions Our experienced sales team and application engineers will deliver the precise support

you need to meet the most demanding and unique requirements. We have the capability to design custom built "special" screw jacks to suit each customer's needs.

Visit us at www.uniliftjacks.com

▼ SELECTION CHART

Capacity (ton)	Model Number	Load Screw Diameter (in)	Lead of Screw (in)	
.25	MA5	0.500	0.250	
.75	MA15	0.625	.250/.125	
1	MA20	0.750	0.200	
1	M1	0.750	0.250	
2	M2	1.000	0.250	
3	M3	1.000	0.250	
4	M4	1.500	0.333	
5	M5	1.500	0.375	
8	M8	1.750	0.333	
10	M10	2.000	0.500	
15	M15	2.250	0.500	
20	M20	2.500	0.500	
25	M25	2.750	0.500	
30	M30	3.375	0.667	
40	M40	4.250	0.667	
50	M50	4.250	0.667	
75	M75	5.000	0.667	
100	M100	6.000	0.750	
150	M150	Contact		
250	M250	Contact		

▼ This is how an M-Series Machine Screw Jack is configured:

Μ	1	U	Т	024	40	L	Τ		<mark>A11</mark>	B1	L22	M5	Ν	S 2	
1	2	3	4	5		6	7		8	9	10	11	12	13	•
1 Mo	del Typ	be		4	Scre	w Con	figura	tion							11 Motor Specifications
M =	Mach	ine Scr	ew Jacl	<	T = 1	Fransla	ating			Thi	rd Digit				First Digit
2 Tor	n Ratin	a			R = 1	Rotatir	ng			1	= 56C	тс			M = Motor
A5 A15	= .25 To = .75 T	<u>o</u> n (alun Fon (alu	ninum) iminum) 5	A = A K = 1	Anti-Ba Keyed	acklast Transl	n** ating) ath (ESL)	3	= 182/184 = 182/184	C TC			Second & Third Digits 1 = 1/4 hp, 1750 RPM 2 = 1/4 hp, 1140 RPM
A20) = 1 To	n (alum	iinum)	5	Exter	lueu a		Leng		5	= 213/215	C			3 = 1/3 hp, 1750 RPM
1=	2 Ton				(Do no	t inclu	ut valu Ide dei	ie (in cima	.) Lin nart	0	= 213/215				4 = 1/3 hp, 1140 RPM
3 =	3 Ton				No	all data	a will b	e ba	sed on 1	<u>9 E</u>	Boot Speci	fications	***		5 = 1/2 hp, 1750 RPM 6 = 1/2 hp, 1140 RPM
4 =	4 Ton				decim	al plac	ce)			Firs	st Digit I – Root				6 = 1/2 np, 1140 RPM 7 = 3/4 hp, 1750 RPM
5 =	5 Ton				Exam	ple: 12	2.0'' = 0)120		Sou	ond Diait				8 = 3/4 hp, 1140 RPM
o = 10 =	= 10 Toi	n		6	Gear	Ratio				1	= 1 Boot. I	No Guides	6		9 = 1 hp, 1750 RPM
15 -	= 15 To	n			$\mathbf{L} = \mathbf{L}\mathbf{c}$	w.				2	= 2 Boots,	No Guide	es		10 = 1.10, 1140 RPM 11 = 1.5 hp. 1750 RPM
20 =	= 20 To	n			$\mathbf{M} = \mathbf{N}$	ledium	٦			3	= 1 Boot, \	With Guid	es		12 = 1 hp, 1140 RPM
25 =	= 25 To	n			n = n	ign				4	= 2 Boots,	With Guid	des		13 = 2 hp, 1750 RPM
30 =	= 30 TO - 40 To	n n		7	End (Config	uratio	n		10	Limit Swit	tch Config	gurati	on	14 = 2 hp, 1140 RPM
50 =	= 50 To	n			$\mathbf{V} = T\mathbf{I}$	reade	d End			Firs	st Diait		-		15 = 3 np, 1750 RPM 16 = 3 hp, 1140 RPM
75 =	= 75 To	n			$\mathbf{C} = \mathbf{C}$	levis E	nd d****			L	. = Limit Sw	/itch			17 = 5 hp. 1750 RPM
100	= 100	Ton			$\mathbf{r} = \mathbf{r}$	an Plat	u e			Sec	cond Digit				18 = 5 hp, 1140 RPM
150	= 150	Ton				•				1	= Right Ha	and Positio	on, 1		19 = 7.5 hp, 1750 RPM
250	= 250	Ion		8	Moto	r Adaj	ptor			2	= Right Ha	and Positio	on, 2		20 = 10 hp, 1750 RPM
3 Mo	unting	Style		F	rst Dig	lit otor A	dantar			3	= Right Ha	and Position	on, 3		12 Stop Nut
U =	= Uprig	ht		S	A = IV	Diait	uaptor			5	= Left Han	d Positior	ייי, ד ו, 1		N = Stop Nut
	= Invert	ed Io Clovi	o *	0	1 = Ri	aht-Ha	and Mo	ount		6	= Left Han	d Positior	ı, 2		
0	- Doub	le Clevi	5		2 = Le	ft-Har	nd Mou	int		7	= Left Han	d Positior	າ, 3		13 Single Shaft
*Double **Anti-F	e Clevis o Backlash	options a	re availat are availa	ole on mo	dels: M	2, M3, N 12 M5	M4, M5, M10_M	M8, M	M10, M15, M	8 ^{И20} Тh	= Left Han ird Digit	d Positior	ז, 4		First Digit S = Shaft
*** Stan	dard Boo	ot materia	al is Neo	prene, alt	ernate r	naterial	s are av	ailable	e, see page	62 - 1	= 2 Circuit	Series 36	50 140		Second Digit
cons **** Plai	sult facto n end for	ry for boo	ots on ro	tating jac lv.	KS					3	= 2 Circuit	Series 43	820		1 = Right Hand 2 - Left Hand
			,	,											

Gear Center (in)		Gear Rati (in)	0	Turns	of Input S 1 inch	Shaft -	Torot	Torque Required to Lift 1 lbs. (in-lbs)			Maximum Input RPM	n Estimated M Weight (Ibs)		Radius of Gyration (in)	Model Number
	Low	Med.	High	Low	Med.	High	Low	Med.	High			0" Travel	Per Inch		
0.938	5:1	-	-	20	-	-	0.022	-	-	2.0	2587	2	0.1	0.094	MA5
0.938	5:1	-	5:1	20	-	40	0.020	-	0.015	2.0	2587	2	0.1	0.125	MA15
1.250	5:1	_	20:1	25	-	100	0.020	Ι	0.010	4.0	2587	5	0.5	0.154	MA20
1.500	5:1	-	10:1	20	-	40	0.021	-	0.013	3.0	2587	9	0.2	0.156	M1
1.750	6:1	_	24:1	24	-	96	0.020	-	0.009	5.0	1800	17	0.6	0.218	M2
1.831	6:1	8:1	12:1	24	32	48	0.021	0.017	0.013	4.0	1800	13	0.4	0.218	M3
2.256	5 ¹ ∕₃:1	12:1	24:1	16	36	72	0.030	0.018	0.012	5.0	1800	23	0.7	0.334	M4
2.188	6:1	-	24:1	16	-	64	0.028	-	0.011	12.0	1800	30	0.7	0.316	M5
3.010	6:1	_	12:1	18	-	36	0.030	-	0.019	7.0	1800	47	0.9	0.396	M8
2.598	8:1	-	24:1	16	-	48	0.029	-	0.015	18.0	1800	45	1.1	0.423	M10
2.598	8:1	_	24:1	16	-	48	0.031	-	0.015	18.0	1800	55	1.2	0.486	M15
2.875	8:1	-	24:1	16	-	48	0.033	-	0.021	36.0	1800	80	1.7	0.566	M20
4.005	9:1	-	18:1	18	-	36	0.031	-	0.019	10.0	1450	103	2.1	0.628	M25
3.750	103:1	-	32:1	16	-	48	0.034	-	0.017	48.0	1200	145	2.9	0.743	M30
5.162	-	_	20:1	-	-	30	-	-	0.024	12.0	1200	230	5.0	0.985	M40
5.313	103:1	-	32:1	16	-	48	0.040	-	0.021	96.0	1200	280	5.0	1.074	M50
6.003	10⅔:1	-	32:1	16	-	48	0.042	-	0.021	156.0	900	495	6.3	1.149	M75
7.500	12:1	-	36:1	16	-	48	0.045	-	0.024	204.0	900	845	7.4	1.387	M100
						C	ontact I		®						M150
						C	Unidel (M250

MA5 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications						
		Gear Ratio	Turns/Inch				
.50" dia. X .25" lead	Low	5:1	20				

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches. Aluminum housing is standard on MA5, MA15 and MA20 Screw Jacks. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating

Clevis End Threaded End Top Plate Ø .28 THRU 4 PLACES 90° APART ON A Ø 1.50 B.C. Ø 2.25 .38 Ø .203 3/8-24 UNF ŧ. .38 Ł Γ́Γ .75 .75 .31 -.75 Ŧ 2.00 Ŧ 1.62 -Ø .50 TRAVEL Ø .50 ESL OPTIONAL BOOT CLOSED: 3.13 CLOSED: 4.00 -1.000 2.38 ESL + .55 Ø.88-

UNI-LIFT[®]



Maximum Speed: 129 in/min

Inverted Rotating



Upright Rotating

Plain End



16 www.uniliftjacks.com

MA15 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications						
		Gear Ratio	Turns/Inch				
5/8" dia. X .25" lead	Low	5:1	20				
5/8" dia. X .125" lead	High	5:1	40				

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches. **For keyed Screw Jacks, add 0.34" to Screw Jack housing height. Aluminum housing is standard on MA5, MA15 and MA20 Screw Jacks. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating





Maximum Speed: 129 in/min

Inverted Rotating



Upright Rotating



MA20 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications						
		Gear Ratio	Turns/Inch				
2/4" dia X 200" laad	Low	5:1	25				
5/4 Ula. A .200 leau	High	20:1	100				

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.0" to the pipe length. ** For keyed Screw Jacks, add 0.57" to Screw Jack housing height.

Aluminum housing is standard on MA5, MA15 and MA20 Screw Jacks. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating



UNI-LIFT®



1 ton Maximum Travel:

230 inches

Maximum Speed: 104 in/min

Inverted Rotating



Upright Rotating



M1 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
3/4" dia. X .250" lead	Low	5:1	20
	High	10:1	40

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.0" to the pipe length. ** For keyed Screw Jacks, add 0.16" to Screw Jack housing height.

Please see page 15 for ordering Matrix.



Inverted Translating



Upright Translating





Inverted Rotating



Upright Rotating



M2 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
1.00" dia. X .250" lead	Low	6:1	24
	High	24:1	96

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.28" to the pipe length. **For keyed Screw Jacks, add 0.06" to Screw Jack housing height. Optional Double Clevis is available. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating

Clevis End

Threaded End

Top Plate



UNI-LIFT®



Capacity: **2 ton**

Maximum Travel: 232 inches

Maximum Speed: **75 in/min**

Inverted Rotating



Upright Rotating



M3 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
1.00" dia. X .250" lead	Low	6:1	24
	Medium	8:1	32
	High	12:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.28" to the pipe length. ** For keyed Screw Jacks, add 0.31" to Screw Jack housing height. Optional Double Clevis is available. Please see page 15 for ordering Matrix.

Top View



Inverted Translating



Upright Translating

Clevis End









Capacity: 3 ton

Maximum Travel: 229 inches

Maximum Speed: 75 in/min

Inverted Rotating



Upright Rotating



M4 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
1-1/2" dia. X .333" lead	Low	51⁄3:1	16
	Medium	12:1	36
	High	24:1	72

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.45" to the pipe length. ** For keyed Screw Jacks, add 0.56" to Screw Jack housing height. Optional Double Clevis is available. *Please see page 15 for ordering Matrix.*

Top View



Inverted Translating



Upright Translating Clevis End

Top Plate



Threaded End

M4 Series

Capacity: 4 ton

Maximum Travel: 228 inches

Maximum Speed: 113 in/min

Inverted Rotating



Upright Rotating Plain End



M5 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
1-1/2" dia. X .375" lead	Low	6:1	16
	High	24:1	64

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.45" to the pipe length. ** For keyed Screw Jacks, add 0.33" to Screw Jack housing height. Optional Double Clevis is available. Please see page 15 for ordering Matrix.



Inverted Translating



Upright Translating





Capacity: 5 ton

M5

Maximum Travel: 230 inches

Maximum Speed: **113 in/min**

Inverted Rotating



Upright Rotating Plain End





M8 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
1-3/4" dia. X .333" lead	Low	6:1	18
	High	12:1	36

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.06" to the pipe length. ** For keyed Screw Jacks, add 0.36" to Screw Jack housing height. Optional Double Clevis is available. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating



UNI-LIFT[®]



Capacity: 8 ton

Maximum Travel: 226 inches

Maximum Speed: 100 in/min

Inverted Rotating



Upright Rotating



M10 Series, Machine Screw Jack

M10

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
2.00" dia. X .500" lead	Low	8:1	16
	High	24:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.06" to the pipe length. ** For keyed Screw Jacks, add 0.75" to Screw Jack housing height. Optional Double Clevis is available. Please see page 15 for ordering Matrix.



Inverted Translating



Upright Translating





Capacity: 10 ton

Maximum Travel: 228 inches

Maximum Speed: **113 in/min**

Inverted Rotating



Upright Rotating

Plain End



UNI-LIFT[®] 25

M15 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
2-1/4" dia. X .500" lead	Low	8:1	16
	High	24:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.06" to the pipe length. ** For keyed Screw Jacks, add 0.67" to Screw Jack housing height. Optional Double Clevis is available. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating



UNI-LIFT®



Capacity: **15 ton**

Maximum Travel: 224 inches

Maximum Speed: 113 in/min

Inverted Rotating



Upright Rotating



M20 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
2-1/2" dia. X .500" lead	Low	8:1	16
	High	24:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.05" to the pipe length. ** For keyed Screw Jacks, add 1.08" to Screw Jack housing height. Optional Double Clevis is available. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating



Top Plate





Capacity: **20 ton**

Maximum Travel: 224 inches

Maximum Speed: 113 in/min

Inverted Rotating



Upright Rotating





M25 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
2-3/4" dia. X .500" lead	Low	9:1	18
	High	18:1	36

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.25" to the pipe length. Please see page 15 for ordering Matrix.

Top View



Inverted Translating



Upright Translating

Top Plate



UNI-LIFT[®]



Capacity: 25 ton

Maximum Travel: 223 inches

Maximum Speed: 81 in/min

Inverted Rotating



Upright Rotating Plain End



M30 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
3-3/8" dia. X .667" lead	Low	10⅔:1	16
	High	32:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches. * If optional stop nut is installed, add 2.07" to the pipe length. ** For keyed

Screw Jacks, add 1.43" to Screw Jack housing height. Please see page 15 for ordering Matrix.



Inverted Translating



Upright Translating





Inverted Rotating



Upright Rotating Plain End



UNI-LIFT[®] 29

M40 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
4-1/4" dia. X .667" lead	High	20:1	30

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches. * If optional stop nut is installed, add 1.50" to the pipe length. *Please see page 15 for ordering Matrix.*

-14 00 **Top View** -7.00 CLOCKWISE ROTATION RAISES LOAD -6.00 5.00 2.41 -Ø 1.375 12.50 | 15.162 5/16 x 5/32 x 1-7/8 LG KEYWAY 14.50 4.88 5.88 Ø 1.06 4 HOLES -10.00 -12.00

Inverted Translating



Upright Translating

Top



UNI-LIFT[®]



Capacity: 40 ton

Maximum Travel: 222 inches

Maximum Speed: 40 in/min

Inverted Rotating



Upright Rotating Plain End



M50 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
4-1/4" dia. X .667" lead	Low	10⅔:1	16
	High	32:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.25" to the pipe length. ** For keyed Screw Jacks, add 2.50" to Screw Jack housing height. *Please see page 15 for ordering Matrix.*

22.00 **Top View** 11.00 9.88 CLOCKWISE ROTATION RAISES LOAD 8.00 3/8 x 3/16 x 2-1/4 LG KEYWAY 4.95 _ Ø 1.500 5.313 9.75 6.00 3.00 4.88 Ø 1.88 4 HOLES 16.00 19.75

Inverted Translating



Upright Translating











Inverted Rotating



Upright Rotating Plain End



UNI-LIFT® 31

M75 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
5.0" dia. X .667" lead	Low	10⅔:1	16
	High	32:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.11" to the pipe length. *Please see page 15 for ordering Matrix.*



Inverted Translating



Upright Translating



UNI-LIFT®



Capacity: **75 ton**

Maximum Travel: 225 inches

Maximum Speed: 56 in/min

Inverted Rotating



Upright Rotating



M100 Series, Machine Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications		
		Gear Ratio	Turns/Inch
6.0" dia. X .750" lead	Low	12:1	16
	High	36:1	48

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches. * If optional stop nut is installed, add 4.5" to the pipe length.

Please see page 15 for ordering Matrix.



Inverted Translating



Upright Translating









UNI-LIFT[®] 33

6.000

F^{1.50}

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ESL

13.07

Ø 8.00

ESL + 18.07

B-Series Section pages Overview

UNI-LIFT[®]

UNI-LIFT Ball Screw Jacks provide high efficiency and high speed in a linear positioning package up to 100 tons. The low friction ball screw and nut design provides longer life at load and requires less power to achieve a specified thrust and movement. Ball Screw Jacks can be used individually, in tandem or as part of a larger mechanical system. With lifts up to 20 feet, UNI-LIFT Ball Screw Jacks offer the perfect solution to a wide range of linear positioning applications.



Ball Screw Cutaway

Screw End Configurations

- Variety of end configurations are available including: threaded, clevis, plain and top plate.
- Bearing journal on end of load screw for rotating jacks provides better column stability

High Strength Roll-Formed Thread Load Screws

- Provides 95% efficiency for minimum input force to position loads
- Ball Screw is rolled and hardened for strength and wear resistance

Tapered Roller Bearings

- Preloaded for reduced assembly spring rate and high thrust loads
- Provides excellent support for side loading and horizontal applications
- Maintains exact gear alignment under separating and thrust forces
- Bearings sized for endurance and maximum loading conditions

High Strength Gearing

- Precision gears manufactured to American Gear Standards with close tolerances and minimal backlash
- Heat treated worm gear set provides greater efficiency, higher input speed, and extended life

Rugged Housings

- Robust ductile iron construction
- Low closed height design saves space, reduces weight, and allows these Ball Screw Jacks to fit into tight areas
Ball Screw Jack Overview



Contact UNI-LIFT!

Contact the UNI-LIFT office nearest to you for advice and technical assistance in the layout of your ideal UNI-LIFT System. You can also ask UNI-LIFT for assistance.

CONTACT INFORMATION:

Customer Service: (630) 408-9349 Toll Free: (888) 984-1924 sales@uniliftjacks.com



Technical Calculations

For Technical Calculations, such as torque and motor sizing please see our "Technical Information Section". 64



65



Frequently Asked Questions

To get answers to frequently asked questions please see our "Technical Information Section". Page:

Capacity (ton)	Series	Page
Technical S	36 🕨	
Ordering Ma	atrix	37 🕨
1	38 🕨	
2	B2	39 🕨
5	B5	40 🕨
10	B10	41 🕨
20	B20	42 🕨
30	B30	43 🕨
50	B50	44 🕨
75	B75	45 🕨
100	B100	46 🕨

B-Series, Ball Screw Jacks

UNI-LIFT[®]

Ball Screw Jacks



- · Ideal for high speeds and continuous cycle applications
- Ball screw design allows for reduced horsepower requirements
- Reduced friction provides extended service life and lower operating costs
- Integrated ball bearing design reduces operating temperatures
- Precision screw lead offers exact positioning for multiple Screw Jack systems

<u>Capacity:</u> **1-100 ton**

Maximum Travel: 230 inches

Maximum Speed: 175 in/min



System Accessories

Provides all the additional components you need to complete your system arrangement.





Customized Solutions

Our experienced sales team and application engineers will deliver the precise support

you need to meet the most demanding and unique requirements. We have the capability to design custom built "special" screw jacks to suit each customer's needs.

Visit us at www.uniliftjacks.com

V SELECTION CHART

Capacity (ton)	Model Number	Load Screw Diameter	Lead of Screw (in)	
1	B1	0.750	0.500	
2	B2	1.000	0.250	
5	B5	1.500	0.474	
10	B10	1.500	0.474	
20	B20	2.250	0.500	
30	B30	3.000	0.667	
50	B50	4.000	1.000	
75	B75	4.000	1.000	
100	B100	4.000	1.000	



Configure Your B-Series Machine Screw Jack

If you cannot configure your standard B-Series Screw Jack using the Matrix, please contact UNI-LIFT for further assistance. Customer Service: (630) 408-9349

Toll Free: (888) 984-1924 sales@uniliftjacks.com

Ball Screw Jack Ordering Matrix

▼ This is how a B-Series Ball Screw Jack is configured:

23 N 2 6 1 Model Type 6 Gear Ratio 9 Boot Specifications** 11 Motor Specifications **B** = Ball Screw Jack $\mathbf{L} = Low$ First Digit First Digit H = High B = Boot M = Brake Motor*** 2 Ton Rating Second Digit Second & Third Diaits 7 End Configuration **1** = 1 Ton 1 = 1/4 hp, 1750 RPM 1 = 1 Boot, No Guides V = Threaded End 2 = 2 Ton 2 = 2 Boots, No Guides **2** = 1/4 hp, 1140 RPM **5** = 5 Ton C = Clevis End **3** = 1/3 hp, 1750 RPM **3** = 1 Boot, With Guides **10** = 10 Ton **P** = Plain End 4 = 1/3 hp, 1140 RPM 4 = 2 Boots, With Guides 20 = 20 Ton **T** = Top Plate 5 = 1/2 hp, 1750 RPM **30** = 30 Ton 10 Limit Switch Configuration **6** = 1/2 hp, 1140 RPM 8 Motor Adaptor **50** = 50 Ton **7** = 3/4 hp, 1750 RPM First Digit First Digit 75 = 75 Ton 8 = 3/4 hp, 1140 RPM A = Motor Adaptor L = Limit Switch 100 = 100 Ton **9** = 1 hp, 1750 RPM Second Digit Second Digit 3 Mounting Style **10** = 1 hp, 1140 RPM 1 = Right-Hand Position, 1 1 = Right-Hand Mount **11** = 1.5 hp, 1750 RPM **U** = Upright 2 = Right-Hand Position, 2 **2** = Left-Hand Mount **12** = 1 hp, 1140 RPM 3 = Right-Hand Position, 3 I = Inverted Third Digit **13** = 2 hp, 1750 RPM **D** = Double Clevis * 4 = Right-Hand Position, 4 **1** = 56C 14 = 2 hp, 1140 RPM 5 = Left-Hand Position, 1 4 Screw Configuration 2 = 143/145TC **15** = 3 hp, 1750 RPM 6 = Left-Hand Position, 2 **3** = 182/184C **16** = 3 hp, 1140 RPM T = Translating 7 = Left-Hand Position, 3 **4** = 182/184TC **17** = 5 hp, 1750 RPM **R** = Rotating 8 = Left-Hand Position, 4 **18** = 5 hp, 1140 RPM **5** = 213/215C 5 Extended Screw Length (ESL) Third Diait **19** = 7.5 hp, 1750 RPM 6 = 213/215TC **1** = 2 Circuit Series 360 **xxx.x** = Input Value (in.) **20** = 10 hp, 1750 RPM 2 = 2 Circuit Series 1440 (Do not include decimal in 12 Stop Nut 3 = 2 Circuit Series 4320 part No. - all data will be N = Stop Nut based on 1 decimal place) Example: 12.0" = 0120" 13 Single Shaft First Digit *Double Clevis options are available on models: B2, B5, B10 S = Shaft **Standard Boot material is Neoprene, alternate materials are available, see page 62 - consult Second Digit factory for boot options on rotating jacks 1 = Right Hand *** All B-series jacks use brake motors when configured at the factory 2 = Left Hand



Ball Screw Recommendations

Ball Screw Jacks are non-locking. Brakes must be used to maintain position. To determine the required braking torque see page 76.



Rotation Prevention Rotation of Load Screw

or Traveling Nut must be prevented in order to produce travel (linear motion).

Stop Nuts

UNI-LIFT[®] recommends the use of Stop Nuts to provide a positive stop at the end of travel.

Gear Center (in)	Gear Low	Ratio High	Turns of Shaf 1" of Low	of Input t For Rise High	Torque F to Lift (in-	Required 1 lbs. -lb) High	Holding (ft-	Torque lb) High	No Load Torque (in-lbs)	Maximum Input RPM	Estim Wei (Ib 0" Travel	nated ght s) Per Inch	Radius of Gyration (in)	Model Number
1.500	5:1	10:1	10	20	0.024	0.015	1.4	2	4	1800	2.3	0.7	0.154	B1
1.750	6:1	24:1	24	96	0.011	0.005	4	1.5	5	1800	17	0.6	0.205	B2
2.188	6:1	24:1	12.66	50.66	0.018	0.007	14	5	12	1800	35	0.6	0.285	B5
2.598	8:1	24:1	16.88	50.66	0.014	0.007	13	4	18	1800	50	0.8	0.285	B10
2.875	8:1	24:1	16	48	0.015	0.007	27	7	36	1800	85	1.5	0.463	B20
3.750	10⅔:1	32:1	16	48	0.015	0.008	21	5	48	1200	220	2.4	0.620	B30
5.313	10⅔:1	32:1	10.66	32	0.022	0.011	40	10	96	1200	340	2.8	0.835	B50
6.000	10⅔:1	32:1	10.66	32	0.022	0.010	107	24	156	900	590	4.6	0.835	B75
7.500	12:1	36:1	12	36	0.020	0.010	128	50	204	900	960	4.6	0.835	B100

B1 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
2/4" dia X 500" laad	Low	5:1	10	
3/4 ula. A .300 leau	High	10:1	20	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.0" to pipe length.

Please see page 37 for ordering Matrix.







Upright Translating Clevis End





UNI-LIFT[®]



Maximum Speed: **180 in/min**



Ball Screw Recommendations

Ball Screw Jacks are nonlocking. Brakes must be used to maintain position.

Inverted Rotating



Upright Rotating Plain End



B2 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications				
		Gear Ratio	Turns/Inch		
1.00 dia X.250" lood	Low	6:1	24		
1.00 ula. A .250 leau	High	24:1	96		

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.28" to pipe length.

Optional Double Clevis is available.

Please see page 37 for ordering Matrix.





Upright Translating









B5 Series, Ball Screw Jack

▼Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
1 1/2" dia X 474" laad	Low	6:1	12.66	
1-1/2 Ula. A .4/4 leau	High	24:1	50.66	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.45" to pipe length.

Optional Double Clevis is available.

Please see page 37 for ordering Matrix.

Top View







Upright Translating







40 www.uniliftjacks.com

B10 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
1-1/2" dia. X .474" lead	Low	8:1	16.88	
	High	24:1	50.66	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 1.37" to pipe length.

Optional Double Clevis is available.

Please see page 37 for ordering Matrix.



Inverted Translating



Upright Translating





B20 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
2 1/4" dia X 500" load	Low	8:1	16	
2-1/4 Ula. X .300 leau	High	24:1	48	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 2.52" to pipe length.

Please see page 37 for ordering Matrix.

Top View



Inverted Translating



Upright Translating



UNI-LIFT®

B20 Series



Capacity: 20 ton

Maximum Travel: 223 inches

Maximum Speed: 113 in/min



Ball Screw Recommendations

Ball Screw Jacks are nonlocking. Brakes must be used to maintain position.

Inverted Rotating



Upright Rotating Plain End



B30 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
2.00" dia X 667" load	Low	10⅔:1	16	
5.00 ula. A .007 leau	High	32:1	48	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 3.5" to pipe length.

Please see page 37 for ordering Matrix.







Upright Translating





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8.25

B50 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
/ 00" dia X 1 0" lead	Low	10⅔:1	10.66	
4.00 dia. X 1.0 lead	High	32:1	32	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

 * If optional stop nut is installed, add 4.0" to pipe length.

Please see page 37 for ordering Matrix.







Upright Translating



UNI-LIFT[®]



4.750

Inverted

Rotating

9.50

B75 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
4 00" dia X 1 0" lead	Low	10⅔:1	10.66	
4.00 Gla. X 1.0 lead	High	32:1	32	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 4.0" to pipe length.

Please see page 37 for ordering Matrix.





Inverted Rotating

Upright Translating





Upright Rotating Plain End



UNI-LIFT[®] 45

B100 Series, Ball Screw Jack

▼ Technical Specifications

Screw Specifications	Gear Specifications			
		Gear Ratio	Turns/Inch	
4.00" dia X 1.00" load	Low	12:1	12	
4.00 Ula. A 1.00 leau	High	36:1	36	

NOTES: For inverted models, add the thickness of the mounting structure to the extended screw length (ESL). All dimensions shown in inches.

* If optional stop nut is installed, add 4.0" to pipe length.

Please see page 37 for ordering Matrix.





Upright Translating



UNI-LIFT[®]



Accessory Overview

From a single screw jack to a multi-screw jack system, a comprehensive range of accessories is available to tailor your UNI-LIFT® system to meet your project requirements.

With a complete line of hand wheels, motors, motor adaptors, rotary limit switches, worm gear reducers, mitre gear boxes, couplers, shafting, screw end adapters, pillow blocks, rotary limit switches, electrical controls and boots – UNI-LIFT[®] can provide the accessories you need to compliment your mechanical screw jack system and to ensure the efficient operation, extended life and safety of your screw jack system.



Components	Series		Page
Hand Wheels	UHW	6	48 🕨
Motors	UM		49 🕨
Motor Adaptors	UMA		50 🕨
Worm Gear Reducers	UGR		52 🕨
Mitre Gear Boxes	UMG	6	54 🕨
Couplers	UC	8	56 🕨
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UNI-LIFT[®] 47

UHW-Series, Hand Wheels

UNI-LIFT[®]

Shown: UHW-34



- Cast iron with chrome plating or aluminum alloy for rigorous applications
- Recessed hub and 3 spoke design provides ample clearance
- Revolving handle design for smooth and easy rotation
- All hand wheels are bored, keyed, and set-screw drilled to provide easy installation

UHW Series

Shaft Sizes: 3/8-3/4 inch

Wheel Diameter: 4-10 inches



Wheel Diameter

As the required input torque increases, a larger wheel diameter reduces the force required from the operator.



Ball Screw Recommendations

Ball Screw Jacks are non-locking. Brakes must be used to hold screw into position.



Special Requests

Aluminum Alloy or larger hand wheels (diameters up to 20") are available upon request. Please contact UNI-LIFT at: sales@uniliftjacks.com

To tension cables, precise positioning in small increments is required. This Hand-Wheel driven 40-ton M-Series UNI-LIFT's[®] smooth operation was the perfect choice for this application.



▼ HAND WHEEL SELECTION CHART

Screw Jack	Bore	Ha	and Wheel Diar	neter Model N	os.
	(in)	4 (in)	6 (in)	8 (in)	10 (in)
MA5, MA15	3/8	UHW34	-	-	-
MA20, M2	1/2	UHW44	UHW46	-	-
M1, M3	5/8	UHW54	UHW56	UHW58	-
M4, M5	3/4	-	-	-	UHW610

▼ Shown: UM-5



- Wide range of operating voltages; 208-230/460 VAC, 3-phase
- **TEFC** motor for optimal performance
- Robust, industrial grade heavy-steel frame
- 3-phase motors are ideally suited for reversing direction and speed control

Horse- power	RPM	Motor Model	NEMA Frame	Starting Torque	Running Torque	Brake Motor	Shaft Diameter	Weight
		No.		[1 _{sm]} (in-lbs)	(in-lbs)	Model No.	(in)	(lbs)
0.25	1750	UM1	56C	30	9	UBM1	0.625	18
0.25	1140	UM2	56C	36	13		0.625	19
0.33	1750	UM3	56C	45	12	UBM3	0.625	20
0.33	1140	UM4	56C	53	18		0.625	21
0.5	1750	UM5	56C	63	18	UBM5	0.625	22
0.5	1140	UM6	56C	74	27		0.625	23
0.75	1750	UM7	56C	105	27	UBM7	0.625	25
0.75	1140	UM8	56C	116	40		0.625	32
1	1750	UM9	56HC	85	36	UBM9	0.625	31
1	1140	UM10	56HC	122	54		0.625	37
1.5	1750	UM11	56HC	150	54	UBM11	0.625	34
1.5	1140	UM12	56HC	134	84		0.625	40
2	1750	UM13	56HC	198	72	UBM13	0.625	41
2	1140	UM14	184TC	252	108		1.125	65
3	1750	UM15	182TC	264	108	UBM15	1.125	61
3	1140	UM16	213TC	409	162		1.375	105
5	1750	UM17	184TC	436	180	UBM17	1.125	75
5	1140	UM18	215TC	783	270		1.375	133
7.5	1750	UM19	213TC	488	270	UBM19	1.375	123
10	1750	UM20	215TC	732	360		1.375	138

UM-Series, Motors

UM Series

Power: 0.25-10 hp





Ball Screw Jacks are non-locking. Brakes must be used to hold screw into position.

UMA-Series, Motor Adaptors

UNI-LIFT[®]

V Shown: UMA-1



Solutions For Direct Mounting



Larger Capability

For 50-ton and above motor mounting please contact UNI-LIFT at: sales@uniliftjacks.com

- Direct mount capabilities up to 30-tons
- Designed to NEMA C-Face Standards
- · Direct couple motor to left or right-hand input shaft
- All hardware provided, including coupling



Motors

For the correct motor to power your specific Screw Jack see UNI-LIFT's line of compatible motors.





Contact UNI-LIFT!

Contact UNI-LIFT for advice and technical assistance in the layout of your ideal UNI-LIFT System: sales@uniliftjacks.com

▼ Motor Adaptors are the ideal solution to couple the motor directly to the 5-ton Double-Clevis Screw Jacks, with a Motor and a Limit Switch Box mounted on each Screw Jack.





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Visit our web site for additional information: www.uniliftjacks.com or contact us at sales@uniliftjacks.com

Motor Adaptors





Right-hand mount shown.



V MOTOR DIMENSIONAL CHART

Screw Jack	Model No.	Motor Frame	Α	В	С	D	E	Weight
model No.			(in)	(in)	(in)	(in)	(in)	(lbs)
M1/B1/M3	UMA1	56C	0.63	0.19	6.5	6.28	4.72	11
M1/B1/M3	UMA2	143TC, 145TC, 182C, 184C	0.88	0.19	6.5	6.28	4.72	11
M2/B2	UMA3	56C	0.63	0.19	6.5	6.65	4.73	11
M2/B2	UMA4	143TC, 145TC, 182C, 184C	0.88	0.19	6.5	6.65	4.73	11
M4	UMA5	56C	0.63	0.19	6.5	6.78	4.69	11
M4	UMA6	143TC, 145TC, 182C, 184C	0.88	0.19	6.5	6.78	4.69	11
M4	UMA7	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	7.28	5.19	11
M5/B5	UMA8	56C	0.63	0.19	6.50	7.16	4.28	11
M5/B5	UMA9	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	7.16	4.28	11
M5/B5	UMA10	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	8.25	5.37	15
M8	UMA11	56C	0.63	0.19	6.50	7.38	4.94	11
M8	UMA12	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	7.38	4.94	11
M8	UMA13	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	7.94	5.50	15
M10/B10	UMA14	56C	0.63	0.19	6.50	8.31	4.81	11
M10/B10	UMA15	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	8.31	4.81	11
M10/B10	UMA16	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	8.87	5.37	15
M15	UMA17	56C	0.63	0.19	6.50	8.44	4.81	11
M15	UMA18	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	8.44	4.81	11
M15	UMA19	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	9.00	5.37	15
M20/B20	UMA20	56C	0.63	0.19	6.50	8.53	4.81	11
M20/B20	UMA21	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	8.53	4.81	11
M20/B20	UMA22	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	9.15	5.43	15
M20/B20	UMA23	213TC, 215TC	1.38	0.75	9.00	9.15	5.43	15
M25	UMA24	56C	0.63	0.19	6.50	8.41	5.25	11
M25	UMA25	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	8.41	5.25	11
M25	UMA26	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	8.72	5.53	15
M25	UMA27	213TC, 215TC	1.38	0.75	9.00	8.72	5.53	15
M30/B30	UMA28	56C	0.63	0.19	6.50	9.15	4.81	11
M30/B30	UMA29	143TC, 145TC, 182C, 184C	0.88	0.19	6.50	9.15	4.81	11
M30/B30	UMA30	182TC, 184TC, 213C, 215C	1.13	0.75	9.00	9.88	5.55	15
M30/B30	UMA31	213TC, 215TC	1.38	0.75	9.00	9.88	5.55	15

UGR-Series, Worm Gear Reducers

UNI-LIFT[®]

V Shown: UGRB



- Standard NEMA C-Face mounting flange
- Aluminum alloy housing with heat sink provides maximum cooling efficiencies
- Range from 1/6 20 hp @ 1750 RPM
- Coated with epoxy-polyester paint throughout the reducer for high corrosion resistance
- · Hardened worm shaft offers increased durability
- · Modular construction for easy adaptability
- Maintenance free, pre-filled with synthetic oil for extended life
- Reduction ratios of up to 100:1 are available upon request



Increases

Precision of

Movement

www.uniliftjacks.com Visit our web site for additional assistance or contact UNI-LIFT at: sales@uniliftjacks.com

Flange	Number	A	в	C	D	E
		(in)	(in)	(in)	(in)	(in)
56C	UGRA	2.76	3.54	6.50	1.38	2.76
56C	UGRB	3.15	4.09	6.50	1.57	3.15
143TC, 145TC	UGRC	3.74	5.12	6.50	1.97	3.94
182TC, 184TC	UGRD	4.43	6.02	9.00	2.36	4.72
182TC, 184TC	UGRE	5.10	6.77	9.00	2.76	5.51
213TC, 215TC	UGRF	6.30	8.27	9.00	3.35	6.69

V WORM GEAR DIMENSIONAL CHART

Worm Gear Reducers

▼ SELECTION CHART

NEMA C	Model	Ratio*	1750 RF	M Input	Input	1140 RF	M Input	Input
Flange	Number		Ou ^r RPM	tput	-	BPM Out	Torque	-
			10.00	(in-lbs)	(hp)		(in-lbs)	(hp)
	UGRA1	5	350	343	1.78	228	403	1.64
500	UGRA2	7.5	233	403	1.43	152	444	1.23
200	UGRA3	10	175	403	1.10	114	444	0.94
	UGRA4	15	117	403	0.76	76	454	0.67
	UGRB1	5	350	625	3.25	228	757	3.08
500	UGRB2	7.5	233	716	2.51	152	847	2.32
- 56C	UGRB3	10	175	726	1.95	114	847	1.78
	UGRB4	15	117	746	1.40	76	847	1.25
14070	UGRC2	7.5	233	1291	4.53	152	1523	4.18
14310,	UGRC3	10	175	1311	3.49	114	1543	3.21
14510	UGRC4	15	117	1412	2.63	76	1563	2.27
10070	UGRD2	7.5	233	1866	6.47	152	2169	5.88
10210,	UGRD3	10	175	1967	5.17	114	2320	4.77
10410	UGRD4	15	117	2017	3.66	76	2370	3.36
19270	UGRE2	7.5	233	2925	10.03	152	3430	9.19
19470	UGRE3	10	175	3127	8.13	114	3732	7.59
10410	UGRE4	15	117	3631	6.51	76	4236	5.94
010TC	UGRF2	7.5	233	4842	16.60	152	5699	15.28
21310,	UGRF3	10	175	5245	13.64	114	6254	12.71
21510	UGRF4	15	117	5749	10.32	76	6657	9.34



NEMA-C Flange Sizes: 56C-215TC

UGR Series

*Ratios: 5:1-15:1

* Ratios up to 100:1 available upon request.





F	G Output	H Key	I	J	К	L	N	0	S	U	V	W	X	Z	Weight	Model Number
(in)	Shaft (in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(lbs)	
2.81	0.75	³∕16 x 1.5	1.69	3.98	4.78	1.57	7.24	3.62	1.38	0.26	1.18	2.79	0.26	1.97	10	UGRA
3.31	1.00	1⁄4 x 1.5	1.93	4.76	5.67	1.97	7.83	3.92	1.57	0.33	1.38	3.35	0.283	2.36	12	UGRB
4.02	1.125	1⁄4 x 1.88	2.64	5.75	6.85	2.48	9.41	4.70	1.97	0.33	1.67	4.06	0.31	2.83	16	UGRC
4.69	1.25	1⁄4 x 2.25	2.83	6.85	8.07	2.95	10.51	5.26	2.36	0.45	1.77	4.41	0.39	3.39	33	UGRD
5.31	1.375	⁵⁄16 x 2.5	2.91	8.19	9.37	3.54	12.17	6.08	2.76	0.51	1.97	5.12	0.43	4.06	41	UGRE
6.59	1.625	3∕8 x 2.75	3.28	9.94	11.61	4.33	13.54	6.77	3.34	0.55	2.26	5.67	0.63	5.02	59	UGRF



UMG Series, Mitre Gear Boxes

UNI-LIFT®

Shown: UMG5 and UMG3



Aluminum Mitre Box

- Lightweight aluminum housing resists corrosion and provides rigid gear and bearing support
- Stainless steel shafts provide resistance to corrosion
- Spiral bevel gearing allows higher operating speeds
- · Lubricated for life to assure trouble free service
- Universal mounting (5 surfaces) for maximum design flexibility

Heavy-Duty Cast Iron Mitre Box

- Rugged iron housing provides rigid gear and bearing support
- Tapered roller bearing for endurance and strength
- Double lip, spring loaded seals keeps lubricant in and dirt out

Interconnect / Drive Screw Jack Systems





Iron Mitre Box

Iron Mitre Boxes are available with spiral gears if higher speed is required.

V	Mitre Gear Boxes were used extensively
	throughout this aircraft scaffolding system to
	interconnect the drive shafts and motors.



▼ ALUMINUM MITRE BOX SELECTION CHART

Model No.	Maximum Input RPM	Output Torque @ Maximum RPM (in-lbs)	Input hp @ Maximum RPM	A (in)	B (in)	C (in)
UMG1	3600	32	1.8	3.95	1.98	1.25
UMG2	3600	76	4.3	7.25	3.63	2.00
UMG3	3600	180	10.25	10.00	5.00	3.00

▼ IRON MITRE BOX SELECTION CHART

Model No.	Maximum Input RPM	Output Torque @ Maximum RPM	Input hp @ Maximum BPM	A	В	С
		(in-lbs)		(in)	(in)	(in)
UMG4	2400	79	3	7.50	3.75	3.19
UMG5	1150	660	12	10.19	5.09	4.13
UMG6	1150	1320	24	12.25	6.13	5.63
UMG7	850	3260	44	15.81	7.91	8.19
UMG8	690	5130	56	16.09	8.05	8.09
UMG9	1750	9039	250	21.50	10.75	9.50

NOTE: Torque ratings are based upon continuous duty service.

Output capacity may be higher for intermittent duty (contact UNI-LIFT®).

Mitre Gear Boxes

Aluminum Mitre Box



Iron Mitre Box









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D	E*	F	н	I	J	K*	L* Keyway	М	N	0	Shipping Weight	Model No.
(in)	(in)	(in)	(in)	(in)	(lbs)							
2.75	0.59	1.31	1.31	0.66	0.27	0.375	0.47 Lg Flat X 1/32 DP	0.17	1.19	0.88	0.50	UMG1
4.75	1.50	1.88	1.88	0.94	0.27	0.625	³ ⁄16 x ³ ⁄32 x 1 ⁷ ⁄32	0.27	1.88	1.38	2.00	UMG2
7.00	2.00	3.00	3.00	1.50	0.33	0.750	³ /16 x ³ /32 x 1 ⁹ /16	0.33	3.00	2.25	8.25	UMG3

	D	E*	F	G	Н	I	J	K*	L* Kevwav	Shipping Weight	Model No.
	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(in)	(lbs)	
	4.56	1.50	2.88	1.31	3.13	1.56	0.34 Thru	0.625	³ ⁄16 x ³ ⁄32 x 15⁄32	9.00	UMG4
	5.72	2.00	4.25	2.13	4.25	2.13	3/8 - NC	1.000	1⁄4 x 1⁄8 x 1 ²⁵ ⁄32	25.00	UMG5
-	8.47	2.50	4.50	2.25	4.50	2.25	1/2 - NC	1.250	1⁄4 x 1⁄8 x 1 ²⁵ ⁄32	48.00	UMG6
	10.88	3.00	6.50	3.25	6.50	3.25	1/2 - NC	1.375	5⁄16 x 5⁄32 x 25⁄16	88.00	UMG7
·	11.48	3.06	6.50	3.25	6.50	3.25	1/2 - NC	1.500	³ ⁄ ₈ x ³ ⁄ ₁₆ x 2 ¹ ⁄ ₄	115.00	UMG8
	15.00	4.00	8.00	4.00	8.00	4.00	1/2 - NC	2.000	1/2 x 1/4 x 33/4	175.00	UMG9

* Identical for three shafts.



UC-Series, Couplers

UNI-LIFT[®]

Your Screw Jack

Drive Solution

V Shown: Jaw-type couplers



Couplers

- Couplers offer standard shaft-to-shaft connection for general industrial-duty applications
- Fail-safe will still perform if elastomer fails
- Sintered iron jaws provide reliable service for heavy-duty applications
- Wide ambient temperature range: -30° to 160° F
- Maximum angle offset of 1° allowing easy installation



Contact UNI-LIFT

For complete details and availability, contact UNI-LIFT at: sales@uniliftjacks.com

▼ JAW TYPE COUPLER SELECTION CHART

Size			Jaw Typ		Jaw Spider (Material)						
	3/8 1/2 5/8 3/4 7/8				1	1 1⁄/8	11⁄4	1 ¾	Urethane	Hytrel	
1	UC1A	UC1B	UC1C	UC1D	UC1E	-	-	-	-	UCU1	UCH1
2	-	UC2A	UC2B	UC2C	UC2D	UC2E	-	-	-	UCU2	UCH2
3	-	-	UC3A	UC3B	UC3C	UC3D	UC3E	-	-	UCU3	UCH3
4	-	-	—	UC4A	UC4B	UC4C	UC4D	-	-	UCU4	UCH4
5	-	-	-	UC5A	UC5B	UC5C	UC5D	UC5E	UC5F	UCU5	UCH5
6	-	-	-	-	-	UC6A	UC6B	UC6C	UC6D	UCU6	UCH6

▼ GEAR TYPE COUPLER SELECTION CHART

Size		(Gear Sleeve					
	3⁄4	1	1 1⁄/8	1 ¼	1 %	1 ½	1 %	2	
1	UCG1A	UCG1B	UCG1C	UCG1D	-	-	-	-	UCGC1
2	_	UCG2A	UCG2B	UCG2C	UCG2D	UCG2E	UCG2F	UCG2G	UCGC2
3	-	-	-	-	UCG3A	UCG3B	UCG3C	UCG3D	UCGC3
4	_	_	-	_	UCG4A	UCG4B	UCG4C	UCG4D	UCGC4

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Couplers



▼ JAW TYPE COUPLER DIMENSIONS

Size	Max. Torque	Rating (in-lbs)	Max. Bore		Dimensions (in)				
	Urethane	Hytrel	(in)	Α	В	С	D		
1	135	217	1	1.75	0.50	0.82	2.13		
2	216	401	11/8	2.11	0.52	0.82	2.15		
3	291	561	1 ³ ⁄16	2.11	0.52	1.00	2.51		
4	477	792	1%	2.54	0.71	1.06	2.84		
5	626	1134	1%	2.54	0.71	1.38	3.48		
6	1188	2268	11/8	3.32	0.88	1.68	4.22		

UC

Series

Torque Ratings: 135-30,200 in-Ibs

Bore Size: 1/4-31/8 inch



Coupler Ordering

When ordering Couplers, each coupler half and insert/ sleeve must be ordered separately.



Shaft Couplings

Balanced shaft couplings compensate for lateral, axial, and angular misalignment.

By using inserts with different durometers (hardness) it is possible to vary the stiffness and dampening effect of the coupling.



Shafting Options

Standard shafting options are also available.

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▼ GEAR TYPE COUPLER DIMENSIONS

Size	Max. Torque Rating	Max. Bore	Dimensions (in)			
	(in-lbs)	(in)	Α	В	С	D
1	2500	11⁄4	3.31	3.13	2.00	2.00
2	7600	15⁄8	3.75	3.75	2.53	2.38
3	20,200	21/8	4.75	4.25	2.56	3.25
4	30,200	25/8	5.50	4.75	3.06	3.94



Shafting

UNI-LIFT®

▼ Shown: Shaft



- Precision balanced shaft reduces vibration
- No intermediate support bearing required on flexible shaft assemblies
- Spans distances of up to 13 feet

▼ DRIVE SHAFTS DIMENSIONS

Size	Shaft to Shaft Length A (in)		Tube Diameter B	Hub Length C	Hub Diameter D
	(min) (max)		(in)	(in)	(in)
1		157.0	1.10	0.66	1.26
2		157.0	1.38	0.74	1.65
3	157.0		1.90	1.26	2.20
4		157.0	2.36	1.46	2.62
5		157.0	2.99	1.66	3.23
6	157.0		3.54	2.05	4.02
7		157.0	4.72	2.44	5.37



Size	Max. Torque Rating		Bore Code Options Diameter (in)												
	(in-lbs)	0.375	0.500	0.625	0.750	0.875	1.000	1.125	1.250	1.375	1.500	1.625	1.750	1.875	2.000
1	283	А	В	С	—	—	—	-	—	—	—	—	—	-	-
2	372	А	В	С	D	E	F	-	—	—	—	—	—	—	-
3	1328	_	_	С	D	E	F	G	Н	—	—	—	—	—	—
4	3540	—	_	_	D	E	F	G	Н	I	—	—	—	—	-
5	7169	_	—	_	D	E	F	G	Н	I	J	K	L	—	—
6	11,948	—	—	—	—	—	F	G	Н	I	J	K	L	М	Ν
7	19,028	—	—	_	—	—	—	—	—	I	J	K	L	М	Ν
	Key Size	0.125	0.125	0.188	0.188	0.188	0.250	0.250	0.250	0.313	0.375	0.375	0.375	0.500	0.500

US Series

<u>Torque Ratings:</u> 135-30,200 in-lbs

Bore Size: 1/4-31/8 inch

H This is how a Shaft is configured:

US 3 B 0125 C C 1 2 3 4 5 6 <u>1 = Model Type</u> US = Shaft <u>2 = Size</u>

1-7 = See table below for options

<u>3 = Insert</u> B = High Torsional Resistance

4 = Shaft to Shaft Length (A) XXX.X = Input Value (in) Do not include decimal in part number. All data will be based on 1 decimal place. Example: 12.5" = 0125

<u>5 = Bore Size LH</u>

A-N = See table below for options

<u>6 = Bore Size RH</u>

A-N = See table below for options

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Screw End Adaptors

V Shown: **UCE-005, UT-005**



- Clevis design allows for a pinned, pivoting application
- Top Plate design offers a perpendicular mounting surface to easily connect to your structure
- Standard mounting holes assure a secure bolted connection





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Visit our web site for additional assistance or contact UNI-LIFT at: sales@uniliftjacks.com



Screw End Dimensions

Dimensions for Screw End Adaptors can be found in the specific M- and B-Series Screw Jack pages.

▼ SELECTION CHART

Screw Jack Size	Screw End Adaptors Model Nos.		
	Top Plate	Clevis	
MA5	UT005	UCE005	
MA15	UT008F	UCE008F	
MA20, M1, B1	UT008	UCE008	
M2, M3, B2	UT010	UCE010	
M4, M5, B5	UT010	UCE100	
B10	UT101	UCE101	
M8, M10	UT105	UCE105	
M15	UT108	UCE108	
M20, B20	UT112	UCE112	
M25	UT202	UCE202	
M30, B30	UT204	UCE204	
M40	UT300	UCE300	
B50	UT304	UCE304	
M50	UT308	UCE308	

▼ To prevent screw rotation this customer installed a Top Plate Adaptor to mount the 5-ton Screw Jack into the welding fixture.



Electrical Controls

UNI-LIFT[®]

Shown: Electrical Control Box



- All systems feature motor short circuit protection, overload protection, phase loss and a lockable disconnect
- Meets NEMA Type 4 Environmental Ratings
- Operates in both a JOG mode and MAINTAINED (Limit Switch) mode
- Extend, Retract, Stop and E-Stop Pushbuttons
- Visible Short Circuit or Overload trip indication, with external reset
- Listed UL508a Control Panel, with a maximum SCCR rating of 100KA
- UL listed and CE marked components
- Full Voltage Reversing Motor Starters are rated for 2.5 million AC-3 Electrical operations

UEC Series



Horsepower: .25-10 hp



Other voltages and single phase options available upon request.



Contact UNI-LIFT

UNI-LIFT offers a range of custom controls to meet all of your system requirements. Contact us at: sales@uniliftjacks.com



 UNI-LIFT[®] provided onsite support and control to synchronize M-Series, 100-ton Screw Jacks for this ferry docking system.

UR-Series, Rotary Limit Switches

Shown: URS21 Rotary Limit Switch



UR Series

Switch Series: 2 Circuit



-20° F to 150° F



Encoders and Linear Transducers

For precise system control Encoders and Linear Transducers can be included in your UNI-LIFT System design.

Contact us at: sales@uniliftjacks.com



Digital Displays

UNI-LIFT can offer precise digital readouts within 0.010".

Contact us at: sales@uniliftjacks.com

Capacity	:	Switch Series 2 Circuit**								
(ton)	1 (360 max. turns)	2 (1440 max. turns)	3 (4320 max. turns)							
1*	URSA11	URSA12	URSA13							
2	URSA21	URSA22	URSA23							
3	URSA31	URSA32	URSA33							
4	URSA41	URSA42	URSA43							
5	URSA51	URSA52	URSA53							
8	URSA81	URSA82	URSA83							
10	URSA101	URSA102	URSA103							
15	URSA151	URSA152	URSA153							
20	URSA201	URSA202	URSA203							
25	URSA251	URSA252	URSA253							
30	URSA301	URSA302	URSA303							

* Not available with the MA5, MA15, MA20 screw jack. ** 4-Circuit available upon request.



- Geared limit switches monitor the number of revolutions to allow for accurate positioning
- 2 circuit design allows for a controlled stop in the advance and retract positions
- The adjustable cams enable precise positioning of travel limit stops
- 4 circuit models available for increased position control



Rotary Limit Switch Sizing

To calculate the required number of turns, utilize the following formula:

TL = TPI x Rise

TPI - Turns of input shaft for 1 inch of travel

Rise - one way travel (in)

Three standard options are available for each tonnage, after determining your required turns select the next highest option from the table on the right. If the required turns or if your UNI-LIFT's load capacity exceeds the values in the selection table please contact UNI-LIFT.

Example:

20-ton screw jack, 8:1 ratio, 72 inches of rise, TPI = 16

16 x 72 = 1152 turns

1152 turns is less than 1440, therefore, select a No.1440 series Limit Switch

Switch can easily be mounted in any one of these positions. When ordering a Rotary Switch in the Matrix please specify right-hand or left-hand and mounting position number.



UB-Series, Boots

UNI-LIFT[®]

Shown: Assorted Boot Family



- · Protects the lifting screw from dust, dirt and moisture
- Provided with internal or external guides to prevent sagging and with zippers for easy installation or removal
- Flange End Boots are provided with an aluminum back-up plate of the same outer diameter to ensure secure mounting
- Helps maintain proper lubrication
- UNI-LIFT[®] Boots are constructed of tough, stitched neoprene-coated nylon material to provide maximum protection from abrasive elements and other hostile environmental conditions
- Optional special boots for severe duty applications, such as weld splatter and high temperature, are available

Solutions For Tough Environments



Travel Guides

Horizontal or angled applications require guides for travel greater than 24". These guides will keep the boot centered on the load screw to

avoid untimely deterioration. One guide is supplied for each 24" of travel. Boot guides do not require additional load screw length.



Determine the Load Screw Length (ESL)

Extra screw must be included for mounting structure, traveling nut, boot closed height, boot retainer and miscellaneous clearances.

To calculate the closed height of the boot, reference boot drawing on the adjacent page.

Material	Temperature Range	Application Comments
Neoprene Coated Nylon	-40° F to 220° F	Good flexibility, resists oils and greases
Hypalon Coated Polyester	-60° F to 300° F	Good chemical and abrasion resistance
Silicone Coated Fiberglass	-40° F to 550° F	High temperature
Aluminized Fiberglass	-40° F to 550° F	High temperature, weld splatter and good abrasion resistance



www.uniliftjacks.com

Visit our web site for additional assistance or contact UNI-LIFT at: sales@uniliftjacks.com

Boots

	This is h	V This is now a Boot is configured:											
	UB	Μ	С	A20	Ν	G	013						
	1	2	3	4	5	6	7						
	<u>1 = Boot</u> UB = Scre	w Jack	Ĩ	<u>4 = Ton</u> A5 = 4 A15 =	Rating 500 lbs = 1500 l	L Ibs.	5 = Material N = Neoprene Nylor H = Hypalon						
	2 = Screw J	ack Se	ries	A20 =	= 2000 l	bs.	S = Silicone						
	B = Ball S	crew	ew	1 = 1 2 = 2	2 = 2 Ton								
	3 = Mountin	g Style	<u>.</u>	3 = 3 4 = 4	Ton Ton		<u>6 = Application</u> <u>Direction</u>						
	C = Uprig	ht Trans	lating	5 = 5	Ton		G = Guides						
	D = Uprigi E = Uprigi	ht Rota ht Keye	ting d	8 = 8 10 = 1	Ion 10 Ton		N = N	o Guides					
F = Inverted Translating G = Inverted Rotating H = Inverted Keyed			15 = 2 20 = 2 30 = 3	15 = 15 Ton 20 = 20 Ton 30 = 30 Ton			<u>7 = Extended Height</u> Input Value (length in inches,						
				40 = 4	to ion		e.g. 1	$2.3^{\circ} = 013$					

	Screw	Boot Diar	neters (in)	Boot Adaptor
	Jack	Α	В	Model No.
	Model No.	Outside	Inside	
	MA5	4.00	1.00	UBPC
	MA15	4.00	1.00	UBPC
	MA20	4.50	1.50	UBPD
	M1	4.50	1.50	UBPD
ks	M2	5.00	2.00	UBPE
Jac	M3	5.00	2.00	UBPE
6M	M4	5.50	2.50	UBPF
Scr	M5	5.50	2.50	UBPF
ne	M8	6.50	3.50	UBPG
achi	M10	6.50	3.50	UBPG
Ň	M15	6.50	3.50	UBPH
	M20	7.50	4.50	UBPI
	M25	8.00	5.00	UBPJ
	M30	8.00	5.00	UBPJ
	M40	9.00	6.00	UBPK
S	B1	4.50	1.50	UBPD
lac	B2	5.00	2.00	UBPE
Ň	B5	5.50	2.50	UBPF
Scre	B10	5.50	2.50	UBPG
alls	B20	7.50	4.50	UBPI
Ö	B30	8.00	5.00	UBPJ

	Boot Adaptor Plate (including screw)										
Screw Jack Mode		С	D	E	F	G					
Model No.	No.	(in)	(in)	(in)	(in)	(in)					
MA5, MA15	UBPC	2.25	0.19	1.03	1.44	0.19					
MA20, M1, B1	UBPD	2.75	0.50	0.84	1.75	0.28					
M2, M3, B2	UBPE	4.00	0.50	1.06	3.00	0.28					
M4, M5, B5	UBPF	4.50	0.50	1.56	3.50	0.28					
M8, M10, B10	UBPG	5.88	0.50	2.06	4.25	0.28					
M15	UBPH	6.13	0.50	2.32	4.50	0.28					
M20, B20	UBPI	7.00	0.50	2.56	5.00	0.28					
M25, M30, B30	UBPJ	8.75	0.50	3.44	6.00	0.28					
M40	UBPK	9.75	0.50	4.32	8.00	0.36					

UB **Series** Boot Diameter (outside):

4-9 inch

Up to 20 feet



Boot Configuration Detail



Boot Adaptor Plate Detail



Technical Information Overview

UNI-LIFT[®]

UNI-LIFT Technical Information

provides in-depth technical information for UNI-LIFT Screw Jacks.

The technical information pages are designed to help you properly specify the right screw jack for your project. These pages include detailed engineering information that answers frequently asked questions (FAQs), motor sizing guidelines, duty cycle considerations, column buckle and double clevis design information, keyed screw jacks, and much more.

Please take the time to review these pages to ensure your awareness of all necessary information to consider when specifying your screw jack.

GLOBAL LIFETIME WARRANTY STATEMENT

www.uniliftjacks.com

Visit our web site for additional assistance or contact UNI-LIFT at: sales@uniliftjacks.com

UNI-LIFT products are warranted to be free of defects in materials and workmanship.

This warranty does not cover ordinary wear and tear, abuse, misuse, alterations, or the use of improper fluids. Determination of the authenticity of a warranty claim will be made only by UNI-LIFT.

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Frequently Asked Questions



1

- **ASL** = Adjusted screw length (in)
- **C** = Motor brake factor (ft-lbs)
- \mathbf{C}_{d} = Dynamic capacity
- $\mathbf{C}_{h} = Cycles per hour$
- **D** = Stopping distance (in)
- \mathbf{D}_1 = Required duty cycle time per hour
- **D**₂ = Allowable duty cycle time per hour
- \mathbf{D}_{s} = Shaft diameter (in)
- **e**₁ = System arrangement efficiency
- $\mathbf{e}_2 = \text{Reducer efficiency}$
- ESL = Extended screw length
- **F** = Column factor multiplier
- $\mathbf{f} = \text{Unit running load proportion factor}$
- **hp** = Horsepower
- HPe = Estimated horsepower
- K = Column factor
- L = Extended screw length (in)
- L₂ = Duty limit service factor
- L₁₀ = Ball screw life (in)

TABLE OF VARIABLES

- N = Number of screw jacks in the system
- P = Rated capacity of screw jack (lbs)
- **P**₁ = Maximum load (lbs)
- P₂ = Total system load (lbs)
- **P**₃ = Maximum system running load (lbs)
- **P**₄ = Maximum running load on one screw jack (lbs)
- R = Gear reducer ratio
- r = Radius of gyration
- Rise = One way travel under load (in)
- **RPMd** = Desired input speed
- **RPMm** = Motor shaft speed
- **RPMs** = System input speed
- T = Running torque (in-lbs)
- **T**₁ = Unit running torque (in-lbs)
- **T**₂ = System running torque (in-lbs)
- t₂ = Required one way travel time (min)
- $T_a =$ Ambient temperature (deg F)

- Tb = Motor brake torque (ft-lbs)
- Te = Estimated system torque (in-lbs)
- Thb = Hold torque (ft-lbs)
- TL = Turns of limit switch
- **T**_m = Mitre gear box running torque (in-lbs)
- **To** = No load torque (in-lbs)
- **Tp** = Torque required to lift one lb. (in-lbs)
- **TPI** = Turns of the input shaft for 1 inch of travel
- **T**_{rm} = Motor running torque (in-lbs)
- Ts = Static torque (in-lbs)
- Ts₂ = System starting torque (in-lbs)
- **T**_{sm} = Motor starting torque (in-lbs)
- T[x] = Unit run torque on screw jack (in-lbs)
- V = Load screw velocity (in/min)
- V_d = Desired load screw velocity (in/min)

1. Q. What is the difference between a Machine Screw Jack and a Ball Screw Jack?

A. The machine screw jack uses an acme threaded screw that is typically self-locking, meaning it will hold its position without a brake. Ball screw jacks use ball screws to convert rotary motion to linear movement, and require 1/3 the horsepower compared to a machine screw jack. Due to the efficiency of the ball screw, brakes must be used to stop and hold the load screw in position. Brakes are also recommended for use on any screw jack if vibration is present.

2. Q. Why use a Machine Screw vs. a Ball Screw Jack?

A. One type of screw jack is usually better suited to the operating conditions. Typically, fast operating speeds and frequent cycle times may be more suited to a ball screw jack, particularly as the load approaches the rated capacity of the screw jack. High load at slower speeds, less frequent cycles and the ability to hold the load in position when the system is at rest may be better suited for a machine screw jack.

3. Q. What is the input torque requirement for a given output load?

- A. The input torque for a specific load and screw jack model is calculated using the technical specifications and formulas in the catalog. The input torque (inch pounds) is listed for each screw jack model in the "Selection Chart" titled "Torque Required to Lift One Pound" (see pages 13 and 37).
- 4. Q. How do I operate the screw jack?
 - A. Most screw jacks are operated by electric motors, but air motors and hydraulic motors can also be used. Occasionally hand wheels are provided for hand operation.
- 5. Q. How do I size motors and calculate required horsepower?
 - A. The horsepower requirement for UNI-LIFT[®] is calculated using the following equation:

(torque to move the load x input RPM) 63025





Frequently Asked Questions

6. Q. Can I use a larger motor than required?

A. Yes, but it is not recommended. The screw jack or system components could be damaged if an oversized motor is used. Electronic position switches or travel limit controls must be used for each end of travel to stop the motor. If using solid mechanical stops, screw jack components can be subject to shock load conditions and oversize motors can cause catastrophic failure of stops and other components.

7. Q. What is TPI?

A. TPI stands for turns per inch and is listed in the Technical Specifications for each screw jack model. The value associated with TPI is the number of revolutions required to the input shaft to move the load one inch. This is calculated by dividing the screw jack ratio by the lead of the load screw.

8. Q. How do I stop the screw jack at the travel limits?

A. Limit Switches or other controls must be used to shut off the motor when the Screw Jack has reached its full extended or retracted position. The use of Limit Switches or Encoders are recommended to control the extended or retracted position of your Screw Jack travel. Stop Nuts are offered to protect against over extension; however, these are intended for emergency use only. Their continued use can cause severe damage to the screw jack. UNI-LIFT offers, as an option, a standard Rotary Limit Switch for this purpose. Other electronic devices include Encoders and Linear Position Transducers.

9. Q. Can multiple screw jacks be used in a system?

A. Yes, but do not exceed 300% of the rated input torque for a given screw jack. Use the standard catalog formulas to determine input torque and motor size.

10. Q. Can different size screw jacks be used in the same system?

A. Yes, as long as the input turns for 1-inch of travel are equal. This is sometimes done to accommodate varying load conditions.

11. Q. What is the system efficiency?

A. - System Arrangement (e,)

2 screw jack s <mark>y</mark> stem: 95%	4-screw jack system: 80%
3 screw jack system: 90%	6 screw jack system: 75%

Worm Gear Reducers (e,)

5 to 1 = 9 <mark>2</mark> %	10 to 1 = 87%
7.5 to <mark>1 = 9</mark> 0%	<mark>1</mark> 5 to 1= 83%

Right angle mitre efficiency is 95% (e_3)

12. Q. What is the maximum input speed?

A. Most UNI-LIFT screw jacks can be run at 1800 RPM (some run up to 2587 RPM). The catalog sizing procedure correlates the Load vs. Input RPM and Duty Limits and Cycle Times. A gear motor, Helical Gear Reducer or a Worm Gear Reducer is used to reduce the input RPM to the screw jack to provide the required travel speed of the load screw (load screw velocity). Many UNI-LIFT Screw Jacks can be driven directly by 1800, 1150 and 900 RPM motors. Motors and reducers are available mounted directly to many UNI-LIFT models.

UNI-LIFT[®]

13. Q. Can standard UNI-LIFT Screw Jacks be used for continuous duty?

A. Yes. The standard catalog sizing procedure includes the formula for determining the duty limits for each screw jack model. This unique feature allows you to calculate the duty cycle limits of each UNI-LIFT model for your application.

14. Q. What is the duty cycle?

A. Duty cycle is the time it takes the screw jack to heat up under a given set of operating conditions limited to a maximum temperature of 180° F.

15. Q. What causes heat build up in the screw jack?

A. The screw jack is a mechanical gearbox assembly. The friction of the gears, load screw, bearings and seals generate heat while the screw jack is operating. The combination of travel, loading, and input speeds all affect the temperature rise of the screw jack. UNI-LIFT sizing calculations take these variables into account to ensure that you select the right screw jack model for your application.

16. Q. What is the load screw capacity and travel?

A. This is based on the relationship of the screw diameter and the length. Screws in tension are rated for the full capacity of the screw jack. For screws in compression, capacity is limited by the load screw's column strength. The column strength of a screw is reduced as the screw gets longer. Use the maximum extended screw length (ESL) when using the Column Buckle Charts (page 71 & 76) to determine load screw capacity.

17. Q. How do I determine the full-extended screw length?

A. The Extended Screw Length (ESL) is normally equal to the travel. Allowances must be added for the closed height of a boot and the addition of stop nuts or special closed heights. These allowances increase the length of the screw. For inverted screw jacks the thickness of the mounting structure must also be included. This total length (ESL) should be used when determining the column load capacity of the screw jack.

18. Q. Should the load being positioned be guided?

A. It is highly recommended that the load be guided; however, it is not necessary. A guided system will provide more column stability and allow longer load screw travel. Column length is greatly reduced on unguided systems. External load forces, common with unguided systems, are detrimental to the life and operation of the UNI-LIFT.



Frequently Asked Questions



19. Q. Can the screw jack withstand side loading or a bending moment?

- A. Yes, but this is not recommended. Consult UNI-LIFT, if this condition will be present! These types of loads apply greater forces on the load screw and housing assembly causing premature wear. Guides are highly recommended and should be used to eliminate side and bending loads.
- 20. Q. Is there backlash between the load screw and gear nut?
 - A. Yes. This is necessary to allow for sliding or rolling action of the screw through the nut. Anti-Backlash Screw Jacks are available when the backlash needs to be minimized. For further information on Anti-Backlash Screw Jacks refer to page 72. Input torque requirements are greater for Anti-Backlash Design Screw Jacks.

21. Q. Can the screw jack withstand shock loading?

- A. This is not recommended. Oversized screw jacks are required to handle shock loads. Solid thrust bearings are also available in many screw jack models when constant vibration and shock are present in an application.
- 22. Q. What mounting position can the screw jack be mounted?
 - A. UNI-LIFT can be mounted in any position: vertical, horizontal or in-between. A position other than vertical should be noted on inquires and purchase orders since special accommodations may be required.

23. Q. How is the load screw protected?

A. Standard translating screw jacks are fitted with a screw protection tube that stores the screw when the screw jack is in the closed position. Boots are available and recommended to protect the screw in the extended position. Two (2) boots may be required for rotating screw jacks with traveling nuts.

24. Q. How do I attach the load to be positioned to the load screw?

A. For translating screw jacks, the load screw has a standard threaded end that can be used to attach the load. Top Plates or Clevis Ends are also available. For traveling nut designs, the traveling nut has a flange with mounting holes. The screw jack housing has a mounting base and is also available with a clevis mount for double clevis requirements.

25. Q. Will the load screw rotate on translating screw jacks?

A. Yes. On translating screw jacks you need to prevent the load screw from rotating to produce linear motion. This is usually accomplished by incorporating it into the application. If rotation of the screw cannot be prevented in the application design, a keyed configuration is available. Input torque will increase for keyed screw jacks and the capacity is reduced to 25% of rated capacity.

26. Q. What is the maximum UNI-LIFT operating temperature limits?

A. Standard UNI-LIFT Screw Jacks are designed to operate at a temperature range of -20° F to 180° F. However, special grease and seals are available to extend the operating temperature limits to as low as -100° F and as high as 400° F. See page 82 for further information.

27. Q. Can screw jacks be used in food industry applications (USDA)?

A. UNI-LIFT uses USDA approved lubrication for these applications.

28. Q. How do I lubricate a screw jack?

A. Use the proper grease. Fill the gearbox by pumping grease into the grease fittings supplied in the screw jack housing. The screws should have grease applied directly to them with a rag or paintbrush. This must be done as part of a regularly scheduled maintenance program.

29. Q. How do I select the right screw jack?

A. The "Screw Jack Overview" section of this catalog contains an easy to follow guide to Screw Jack selection or contact UNI-LIFT at: sales@uniliftjacks.com

30. Q. What is the position accuracy?

A. 0.010" between activators.

31. Q. What is the best way to contact UNI-LIFT?

A. Call: 888-984-1924 Email: sales@uniliftjacks.com







1. Complete the UNI-LIFT[®] Worksheet located on page 86. See Table 1 for complete details on the technical specifications.

2. Determine the maximum load on one screw jack (P₁, lbs)

 $P_1 = P_2$ = Total system load (lbs)

 \overline{N} N = Number of Screw Jacks in the system On multi-screw jack systems where the load is not equally distributed, P₁ equals the maximum load supported by one screw jack.

3. Select the Screw Jack size

- If the screw is in tension, select an screw jack with a rated capacity equal to or greater than maximum load (P₁) on one screw jack.
- If the load screw is in compression, use the calculation steps, on page 71, to determine the maximum permissible Extended Screw Length (ESL). Select an screw jack that has a load screw length capacity equal to or greater than the length required for the load.

4. Determine the Load Screw Velocity (V_d, in/min)



5. Determine Desired Input Speed: (RPMd)

RPMd = TPI x V_d TPI = Turns of the input shaft for 1 inch of rise (see table on page 69).

6. Determine Load Screw Velocity (V, in/min)

 $V = \frac{\text{RPM}_{\text{d}}}{\text{TPI}}$ From the catalog data (page 52), select the power transmission equipment with an output speed close to the desired input speed (RPM_d). Use the output speed to recalculate the actual load screw velocity.

7. Required Duty Cycle Time (D₁, min)

 $C_{h} = Cycles per hour$

$D_1 = (2^* Travel^* C_h)$

Travel = Distance load will move in one direction (in)

Use the calculation steps on page 70 to determine if D_1 is equal to or greater than D_2 .

If D_{2} is less than D_{1} you must:

- reduce the input speed to the screw jack
- reduce the load by adding additional screw jacks to the system
- Use a larger screw jack

MOTOR AND POWER TRANSMISSION SIZING

Calculate the torque and horsepower requirements using the 7 steps on page 69.

- Select a motor with a power rating greater than System hp requirement, a starting torque greater than $T_{\rm sm}$, and a motor running torque greater than Trm. See page 49 for horsepower and motor ratings.
- Select system Power Transmission equipment (gear reducer, mitre gear boxes, couplings, etc) with ratings greater than the running torque on power transmission equipment (Te), see Application Example on page 80.
- Size shafting for system starting torque $\rm T_{\rm sm}$ to be transmitted, see page 69.

For a quick estimate for torque and motor requirements use the following calculations

$$HPe = (Te*RPM_s) Te = Tp*P_3 63025$$

HPe = Estimated horsepower

Te = Estimated system torque (in-lbs)

 $P_{a} = Maximum system running load (lbs)$

RPM_s = System RPM

RPM_m = Motor RPM

Tp = Torque required to lift 1 lbs. [Table 1]

▼ TABLE 1

	Capacity [P]	Model Number	Tor t	que Requ o Lift 1 lb [Tp]	uired s.	No Load Torque [To]	Radius of Gyration [r]				
	(ton)		Low	(in-lbs) Med.	Hiah	(in-lbs)	(in-lbs)				
F	.25	MA5	0.022	_	_	2.0	0.094				
	.75	MA15	0.020	_	0.015	2.0	0.125				
	1	MA20	0.020	—	0.010	4.0	0.154				
	1	M1	0.021	—	0.013	3.0	0.156				
	2	M2	0.020	—	0.009	5.0	0.218				
	3	M3	0.021	0.017	0.013	4.0	0.218				
	4	M4	0.030	0.018	0.012	5.0	0.334				
	5	M5	0.028	—	0.011	12.0	0.316				
	8	M8	0.030	—	0.019	7.0	0.396				
	10	M10	0.029	—	0.015	18.0	0.423				
	15	M15	0.031	31 — 0.015		18.0	0.486				
	20	M20	0.033	—	0.021	36.0	0.566				
	25	M25	0.031	—	0.019	10.0	0.628				
	30	M30	0.034	_	0.017	48.0	0.743				
	40	M40	-	—	0.024	12.0	0.985				
	50	M50	50 0.040 — 0.021 96		96.0	1.074					
	75	M75	0.042	—	0.021	156.0	1.149				
	100	M100	0.045	—	0.024	204.0	1.387				
	150	M150									
	250	M250									



Calculating the Torque

1. Determine unit running load proportion factor (f)

P = Rated capacity of screw jack
$P_3 = Maximum$ system running load
N = Number of Screw Jacks in the system

2. Determine unit running torque (T₁, in-lbs) [Table 2]

 $T_1 = (T * f) + To$ To = No Load Torque (in-lbs) T = Running torque (in-lbs)**

3. Find the system running torque (T₂, in-lbs)

$$T_2 = (T_1 * N)$$

 $e_1 = System Arrangement Efficiency - see page 66 (question #11)$

4. Find system power, (System hp)

$hp = (T_2 * RPM_s)$	RPM _s = Input shaft speed
(63025 * e)	e ₂ = Reducer efficiency - see
Y 2"	page 66 (question #11)

page 66 (question #11)

5. Determine system starting torque (Ts₂, in-lbs) Ta $= \frac{1}{2} \frac{1$

 $Ts_{2} = [(Ts^{*}f) + To)^{*}N]$ Ts= Static Torque (in-lbs) [Table 2]

6. Determine motor starting torque (T_{sm} , in-lbs) $T_{sm} = Ts_2$ R = Gear Reducer Ratio

$$m = \frac{IS_2}{(R^*e_2)}$$

7. Determine motor running torque (Trm, in-lbs) Trm = T_{2}

(R*e,)

Rated	Model	Gear	Turns Per	er Static Unit Input Torque at Rated Capacity N									No Load
Capacity	Number	Ratio	Inch*	Torque									
[P]			[TPI]	[Ts]	[Ts] T = Running Torque (in-lbs) @ Various RPM _s (theoretical)**								[To]
(ton)					50 RPM	115 RPM	172 RPM	345 RPM	600 RPM	870 RPM	1140 RPM	1750 RPM	(in-lbs)
.25	MA5	5:1	20	11	9	8	8	8	7	7	7	6	2
75	MA15	5:1	20	36	28	26	25	24	23	22	21	20	2
		5:1	40	29	21	20	19	18	17	16	15	14	1.5
1	MA20	5:1	25	48	35	33	32	29	27	26	25	24	4
-	MALV	20:1	100	22	15	14	13	12	11	10	9	8	4
1	M1	5:1	20	54	39	37	36	32	31	29	28	27	3
•		10:1	40	33	23	22	21	19	18	17	16	15	3
2	M2	6:1	24	104	75	70	67	61	57	54	52	49	5
		24:1	96	51	29	27	26	23	21	20	18	17	5
		6:1	24	171	120	111	105	95	88	84	81	76	4
3	M3	8:1	32	141	97	89	85	76	71	67	64	60	4
		12:1	48	111	73	68	64	58	52	49	47	44	4
		5.33:1	16	342	237	215	202	186	172	163	156	146	5
4	M4	12:1	36	211	135	123	117	102	94	88	84	78	5
		24:1	72	155	92	83	78	68	60	55	52	47	5
5	M5	6:1	16	379	270	249	236	217	202	192	185	174	12
		24:1	64	155	100	92	88	79	71	66	63	58	12
8	M8	6:1	18	732	478	429	400	363	333	313	299	276	7
		12:1	36	472	292	264	247	215	196	184	175	162	7
10	M10	8:1	16	831	569	520	492	448	415	393	377	352	18
		24:1	48	443	274	250	236	209	185	173	164	151	18
15	M15	8:1	16	1,356	912	828	773	708	653	616	589	548	18
		24:1	48	723	442	401	377	332	294	273	259	238	18
20	M20	8:1	16	1,920	1,276	1,150	76	982	902	848	809	750	36
		24:1	48	1,003	811	552	519	454	403	375	356	326	36
25	M25	9:1	18	2,371	1,534	1,371	1,279	1,161	1,062	996	948	—	10
		18:1	36	1,528	941	846	792	689	627	586	557	—	10
30	M30	10 3 :1	16	3,067	1,982	1,774	1,656	1,502	1,374	1,289	1,228		48
		32:1	48	1,694	988	883	824	713	627	581	549		48
40	M40	20:1	30	3,226	1,927	1,706	1,581	1,383	1,248	1,160	1,098	—	12
50	M50	10 3 :1	16	6,559	3,915	3,382	3,189	2,838	2,556	2,372	2,244	_	96
	11100	32:1	48	3,721	1,995	1,736	1,595	1,333	1,180	1,084	1,019	_	96
75	M75	10 2 3:1	16	10,171	6,096	5,279	4,975	4,420	3,971	3,676	_	—	156
		32:1	48	5,243	2,920	2,560	2,361	1,998	1,781	1,642	—	—	156
100	M100	12:1	16	15,639	8,767	7,501	7,019	6,165	5,495	5,065		_	204
100	M100	36:1	48	9,115	4,568	3,893	3,535	2,928	2,568	2,349	—	—	204

* Of Input Shaft for 1" of Rise

** When calculating, if actual RPMs is between columns, use the column with the lower RPM value.



M-Series, Duty Cycle Calculations



Duty Limit Service Factor (L_{a}) = Operating time allowed per hour. The numbers greater than 60 are theoretical values and exceed 100% duty, solely to provide base data for adjusting L₂

The L_a values are based on screw jacks loaded at rated capacity, operating in an ambient temperature of 80° F with a maximum allowable temperature rise of 100° F. For ambient temperatures above 180° F or below -20° F consult UNI-LIFT. For speeds not shown use the next fastest RPM value.

1. Determine Allowable Duty Cycle Time (D₂)

When the unit load is at rated capacity, and the ambient temperature is at 80° F the L₂ value from the table equals D₂ If not, proceed to step 1A.

Step 1A

For different temperature service, or a unit load less than rated capacity, use the following equation to determine the Allowable Duty Cycle Time (D₂).

$$D_2 = \frac{[(180 - T_a) * P*L_2]}{(100* P)}$$

 P_4 T_a = Ambient temperature (deg F)

- P = Rated capacity (lbs)
- L₂ Duty limit service factor (see Table 3)**
- P_{A}^{I} = Maximum running load per unit (lbs)

▼ TABLE 3

- 2. Determine if Duty Cycle Time is acceptable
 - If $D_{a} > = 60$ minutes the application is rated for continuous duty
 - If $D_a > = D_a$ than the application is acceptable

If $D_2 < D_1$ than the duty cycle limit has been exceeded for this application. You must do one of the following:

- Reduce the input speed to the screw jack
- Reduce load by adding additional screw jack to the system
- Use a larger size screw jack

If you reduce speed you must recalculate V and D, from page 68 numbers 6 and 7.

See page 75 for an "Example" calculation.

Model	Gear	Turns Per Inch*		L, -	Duty Limit	Service Fa	ctor @ Vari	ous RPM _e I	nput Speed	ls**	
Number	Ratio	[TPI] (in)	50 RDM	115 RDM	172 RDM	345 RDM	600	870 RDM	1140 RDM	1750 RDM	2587 RDM
MA5	5.1	20	071	/61	325	18/	110	88	71	52	30
MAJ	5.1	20	377	152	108	61	20	20	22	17	12
MA15	5.1	20	323	155	110	64	41	29	23	10	10
	5.1	40	325	100	70	45	41	30	24	10	13
MA20	00.1	100	ZZ9 401	250	101	40	29	21 50	17	20	9
	20:1	100	401	200	101	77	40	52	40	01	20
M1	0:1 10:1	20	647	100	017	100	49	50	29	21	10
	10:1	40	647	307	217	122	80	59	48	34	26
M2	011	24	263	120	90	53	33	25	20	15	
	24:1	96	589	297	213	123	81	62	52	38	
MO	6:1	24	143	69	50	29	18	14	14	8	
IVIO	8:1	32	1/6	85	60	36	23	17	14	10	
	12:1	48	228	110	/8	45	30	22	18	13	
	5.33:1	16	109	54	40	23	15	11	9	1	
IVI4	12:1	36	186	91	66	39	25	19	16	11	
	24:1	72	236	118	90	55	37	29	24	18	
M5	6:1	16	133	65	47	27	17	13	11	8	
	24:1	64	336	163	117	67	44	34	28	20	
M8	6:1	18	84	42	31	18	11	9	7	5	
	12:1	36	135	67	48	29	19	14	11	8	
M10	8:1	16	81	40	29	17	11	8	6	5	
	24:1	48	155	77	56	33	22	17	14	10	
M15	8:1	16	52	26	19	11	7	5	4	3	
	24:1	48	100	50	36	21	14	11	9	6	
M20	8:1	16	47	24	17	10	6	5	4	3	
	24:1	48	93	46	33	20	13	10	8	6	
M25	9:1	18	46	23	17	9	6	5	4		
	18:1	36	74	37	26	16	10	7	6		
M30	10 <u></u> 3:1	16	47	23	17	10	6	5	4		
	32:1	48	84	44	32	19	13	10	8		
M40	20:1	30	52	26	19	11	7	5	4		
M50	10 3 :1	16	30	16	11	6	4	3	2		
WIGO	32:1	48	52	28	21	13	9	6	5		
M75	10 <u></u> 3:1	16	30	16	11	6	4	3			
	32:1	48	61	31	23	14	9	7			
M100	12:1	16	31	16	12	7	4	3			
WITOU	36:1	48	54	30	22	14	9	5			

** Of Input Shaft for 1" of Rise ** When calculating duty limit service factor, if the actual RPM_s value is between columns, use the next higher RPM value.
M-Series, Column Buckle Chart



The maximum estimated screw length (ESL) values in the chart below are based on a **2:1 factor of safety against column buckle**, and on a standard design with a top plate or a rotating design travel nut. Increased load screw lengths are not shown where the slenderness ratio exceeds 400.

1. Determine extended screw length (ESL)

The ESL is the distance in inches the load screw can extend from the housing. Allowances must be made when using boots and for other miscellaneous clearances. See catalog for the model selected to determine ESL.

2. Determine the adjusted screw length (ASL)

The chart below is for a standard design top plate or the rotating design travel nut. For other design configurations you must adjust the ESL value using the F factor multiplier to determine the adjusted screw length.

 $ASL = ESL \times F$

3. On the chart below draw a horizontal line to represent the maximum load (P₁). Using the set of ESL values that apply to your design (guided or unguided), draw a vertical line to represent the ESL or ASL. All of the screw jacks above the point of intersection will be acceptable.



Screw lengths with a column buckle above the dotted line in Chart 1 comply with AISC maximum slenderness ratio specified for design and fabrication of structural steel buildings. This data is

for reference only and is not a limiting factor, except as required.

$$\frac{K^{*}L}{r} <= 200$$

K = Column Factor

L = Extended Screw Length (ESL)

r = Radius of Gyration

See Table on page 68 for r values.

▼ TABLE 4

Design Configuration	F Factor	K Factor (Guided) (Unguided)		
Standard Design Top Plate	1	0.65	1.3	
Rotating Design Traveling Nut	1	0.65	1.3	
Standard Design Clevis End	1.25	0.80	1.6	
Keyed Design Top Plate	1.25	0.65	1.3	
Keyed Design Clevis End	2	0.65	1.6	



▼ CHART 1



Anti-Backlash Screw Jacks

UNI-LIFT[®]

Anti-Backlash Designed

The Anti-Backlash design allows the backlash in the lifting screw to be minimized to meet the application requirements by simply adjusting the adjustment plug. Features include: One-piece gear nut, independent adjustment of the thrust bearing preload (to bearing manufacturers recommendations), extra long screw thread engagement, reduced unit spring rate, and full gear tooth contact. This design insures proper bearing alignment and worm gear tooth contact for maximum unit efficiency. The Anti-Backlash is a quality product you can depend on to provide a long operating life.

- Anti-backlash Screw Jack components fit in the same Screw Jack housing with the same mounting footprint as our standard Screw Jacks. Standard units can be field converted.
- ② Full Bearing Guided Drive Sleeve and Correct Gear Alignment provides longer gear life.
- ③ Replaceable Anti-Backlash Adjustment Plug can be replaced without disassembly of the main jack housing assembly.
- ④ True screw backlash can be set without compromising internal housing and bearing backlash tolerances.
- ⑤ Independent Thrust Bearing Adjustment allows the thrust bearings to be independently preloaded, not free to float or allow backlash in the gear nut.
- ⑥ Rigid support of the Worm Gear provides proper alignment for the gear mesh providing full tooth contact and smooth torque transfer.
- ⑦ Long Thread Engagement for both the Drive Sleeve and Adjustment Plug provides long wear life.
- Reduce Unit Spring Rate by Design of Independent Backlash Adjustment reduces the expansion and contraction fluctuations of the internal screw jack components during reversing load conditions.







- Complete the UNI-LIFT[®] Worksheet located on page 86. See Table 5 for complete details on the technical specifications.
- 2. Determine the maximum load on one screw jack (P₁, lbs)

 $P_1 = P_2$ $P_2 = Total system load (lbs)$

N = Number of Screw Jacks in the system On multi-screw jack systems where the load is not equally distributed, change P_1 to the maximum load supported by one screw jack.

3. Select the Screw Jack size

For high-cycle applications, use 80% of rated capacity.

- If the screw is tension, select an screw jack with a rated capacity equal to or greater than maximum load (P₁) on one screw jack.
- If the load screw is in compression, use the calculation steps, on page 76, to determine the maximum permissible Extended Screw Length (ESL). Select an screw jack that has a load screw length capacity equal to or greater than the length required for the load.

Rise = One way travel under load (in)

 t_{o} = Required one way travel time (min)

4. Determine the Load Screw Velocity (V_d, in/min)

 $V_d = Rise$

t,

5. Determine Desired Input Speed: (RPMd)

 $RPMd = TPI \times V_d$ TPI = Turns of the input shaft for 1 inch of rise (see table on page 74).

6. Determine Load Screw Velocity (V, in/min)

 $V = \frac{RPM}{TPI}_{d}$ • From the catalog data (page 52), select the power transmission equipment with an output speed close to the desired input speed (RPM_d). Use the output speed to recalculate the actual load screw velocity.

7. Check the Required Duty Cycle Time (D, min)

 $D_1 = (2^{*} \underline{\text{Travel}^{*}C_h}) C_h = \text{Cycles per hour}$

Travel = Distance load will move in one direction (in)Use the calculation steps on page 75 to

determine if D_1 is equal to or greater than D_2 .

▼ TABLE 5

- If D_2 is less than D_1 you must:
- reduce the input speed to the screw jack
- reduce the load by adding additional screw jacks to the system
- Use a larger screw jack

8. Calculate the Ball Screw life in inches of travel (L_{10} in):

- C_d = Dynamic capacity based on 1 million inches (lbs)
- $P_4 =$ Maximum running load on one screw jack (lbs)

If the application requires longer life select a larger screw jack or increase the number of screw jacks in the system.

 $L_{10} = \left(\frac{Cd^{3}}{P_{4}^{3}}\right)$ 1,000,000

 L_{10} life is based on a 10% wear factor on the load screw and ball nut.

MOTOR AND POWER TRANSMISSION SIZING

Calculate the torque and horsepower requirements using the 8 steps on page 74.

- Select a motor with a power rating greater than System hp requirement, a starting torque greater than T_{sm}, and a motor running torque greater than Trm. See page 49 for horsepower and motor ratings.
- Select system Power Transmission equipment (gear reducer, mitre gear boxes, couplings, etc) with ratings greater than the running torque on power transmission equipment (Te), see Application Example on page 80.
- Size shafting for system starting torque T_{sm} to be transmitted, see page 74.

For a quick estimate for torque and motor requirements use the following calculations $HPe = (Te^*RPM_s) \qquad Te = Tp^*P_3$ $\frac{1}{63025}$ HPe = Estimated horsepowerTe = Estimated system torque (in-lbs) $P_3 = Maximum system running load$ $RPM_s = System RPM$ $RPM_m = Motor RPM$ Tp = Torque required to lift 1 lbs. (Table 1) $RPMs = (RPM_m)$ Reducer Ratio

Capacity [P]	Model Number	Turns p [T	er Inch* PI]	Torque Required to Lift 1 lbs. [Tp] (in-lbs)		Holding Torque [Thb] (ft-lbs)		Radius of Gyration [r]	Dynamic Capacity @ 1 Million Inches [Cd]
(ton)		Low	High	Low	High	Low	High	(in)	(lbs)
1	B1	10.00	20.00	0.024	0.015	1.4	2	0.154	3400
2	B2	24.00	96.00	0.011	0.005	4	1.5	0.205	1625
5	B5	12.66	50.66	0.018	0.007	14	5	0.285	10,050
10	B10	16.88	50.66	0.014	0.007	13	4	0.285	10,050
20	B20	16.00	48.00	0.015	0.007	27	7	0.463	19,300
30	B30	16.00	48.00	0.015	0.008	21	5	0.620	38,000
50	B50	10.66	48.00	0.022	0.011	40	10	0.835	85,000
75	B75	10.66	32.00	0.022	0.010	107	24	0.835	85,000
100	B100	12.00	36.00	0.020	0.010	128	50	0.835	85,000

* Of Input Shaft for 1" of Rise

UNI-LIFT[®] 73



UNI-LIFT®

Calculating the Torque

1. Determine unit running load proportion factor (f)

f	=	P ₃
	(F	^{>∗} N)

P = Rated capacity of screw jack

 $P_3 = Maximum system running load$

N = Number of Screw Jacks in the system

2. Determine unit running torque (T₁, in-lbs) [Table 7]**

 $T_1 = (T * f) + T_0$ $T_o = No Load Torque (in-lbs)$

T[°] = Running torque (in-lbs)

3. Find the system running torque (T₂, in-lbs)

 $T_2 = (\underline{T_1 * N}) = \underline{e_1} = System Arrangement Efficiency - see page 66 (question #11)$

4. Find system power, (System hp)

hp = $\frac{(T_2 * RPM_s)}{(63025 * e_2)}$

 $RPM_s = Input shaft speed e_2 = Reducer efficiency - see page 66 (question #11)$

5. Determine system starting torque (Ts₂, in-lbs)

Ts= Static Torque (in-lbs) [Table 7] See Table 7.

6. Determine motor starting torque (T_{sm}, in-lbs)

 $T_{sm} = \frac{Ts_2}{(R^*e_2)}$ F

R = Gear Reducer Ratio

7. Determine motor running torque (Trm, in-lbs)

 $\operatorname{Trm} = \operatorname{T_2}_{\overline{(\mathsf{R}^*\mathsf{e}_1)}}$

▼ TABLE 7

8.	Determine motor brake torque (Tb, ft-lbs)
	(required for all Ball Screw Jack applications):

$$\left(\mathsf{Tb} = \frac{\mathsf{C}}{(\mathsf{TPI}^*\mathsf{D}^*\mathsf{R})} \right) + \left(\frac{(\mathsf{TPI}^*\mathsf{D}^*\mathsf{R})}{\mathsf{R}} \right)$$

- C = Motor Brake Factor (ft-lbs) (see Table 6) Tb = Motor Brake Torque (ft-lbs)
- Thb = Hold Torque (ft-lbs) (see page 72)
- D = Stopping Distance (in)
- N = Number of Screw Jacks
- R = Gear Reducer Ratio

TABLE 6	
C-Factor for Brake Motor (fi	-lbs)

Motor (hp)	1140 RPM	1725 RPM
1/4	3.20	4.1
1/3	4.00	4.9
1/2	5.10	6.1
3/4	7.89	9.2
1	9.18	17.8
1-1/2	11.30	21.6
2	29.50	25.6
3	38	66.5
5	48.3	87.4
7-1/2	69.4	112
10	126	146
15	268	273
20	306	315
25	548	596

Model	Gear	Turns Per	Static		Unit Input Torque at Rated Capacity								
Number	Ratio	[TPI]	[Ts]	т	T = Running Torque (in-Ibs)								
			(in-lbs)	50 RPM	115 RPM	172 RPM	345 RPM	600 RPM	870 RPM	1140 RPM	1750 RPM	(in-lbs)	
1 B1	5:1	10.00	51	44	43	42	41	40	40	39	38	3	
ы	10:1	20.00	32	26	25	24	23	22	22	21	21	Ũ	
B0	6:1	24.00	43	37	36	35	34	34	33	33	32	5	
DZ	24:1	96.00	19	14	13	13	12	11	11	10	10	Ũ	
R5	6:1	12.66	196	171	167	164	160	156	154	152	150	12	
3 B 5	24:1	50.66	80	60	57	55	52	49	47	46	44	12	
P10	8:1	16.88	322	270	261	256	247	240	236	233	228	18	
10 B10	24:1	50.66	172	125	117	112	105	98	94	91	87	10	
P00	8:1	16.00	667	561	543	534	516	502	493	487	479	36	
D2U	24:1	48.00	348	255	239	230	215	202	194	189	181	00	
B00	10 ₃ :1	16.00	1054	864	832	815	784	760	745	736	—	48	
D 30	32:1	48.00	582	408	379	363	335	312	298	289	—		
BE0	10 ₃ :1	16.00	2700	2150	2058	2011	1929	1870	1836	1814	—	96	
D00	32:1	48.00	1532	1018	932	887	811	755	722	701	—	50	
D76	10 을 :1	10.66	3842	3134	3015	2954	2848	2770	2724	—	—	156	
D/5	32:1	32.00	1981	1384	1284	1232	1141	1074	1035	—	—	150	
B100	12:1	16.00	4977	3846	3660	3568	3414	3307	3248	—	—	204	
D100	36:1	48.00	2901	1837	1663	1575	1429	1327	1271	—	—	204	
	Model Number B1 B2 B5 B10 B20 B30 B30 B50 B75 B100	Model Number Gear Ratio B1 5:1 10:1	Model Number Gear Ratio Turns Per Inch* [TPI] B1 20.00 B1 10.1 20.00 24.00 B2 6.1 24.00 B2 24.1 96.00 B5 24.1 96.00 B4 24.1 50.66 24.1 50.66 24.1 B10 24.1 50.66 24.1 50.66 24.1 B20 8.1 16.00 24.1 50.66 24.1 B20 8.1 16.00 B21 10.2 48.00 B30 32.1 48.00 B50 10.2 48.00 B75 10.2 32.00 B100 32.1 32.00 B100 36.1 48.00	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [Ts] B1	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [TS] Inch* [TPI] Torque [TS] 50 B1 51 10.00 51 44 10:1 20.00 32 26 B2 6:1 24.00 43 37 24:1 96.00 19 14 B5 6:1 12.66 196 171 24:1 96.00 19 14 B5 6:1 12.66 80 60 B10 24:1 50.66 80 60 B10 8:1 16.88 322 270 B20 8:1 16.00 667 561 B20 3:1 16.00 348 255 B30 10\$:1 16.00 1054 864 32:1 48.00 582 408 B50 10\$:1 10.66 3842 3134 32:1 48.00 1532 1018	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [Ts] T B1 5:1 10.00 51 44 43 B1 5:1 10.00 51 444 43 B2 6:1 24.00 43 37 36 B2 6:1 24.00 43 37 36 B4 24:1 96.00 19 14 13 B5 6:1 12.66 196 171 167 B4 16.88 322 270 261 B10 24:1 50.66 80 60 57 B10 8:1 16.88 322 270 261 B20 8:1 16.00 667 561 543 B20 3:1 16.00 1054 864 832 B21 16:00 1054 864 832 B23 10 \$:1 16.00 2700 2150 2058	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [Ts] Turns Per Torque [Ts] Static Torque [Ts] Turns Per Torque [Ts] Unit Inp Torque [Ts] B1 5:1 10.00 51 44 43 42 B1 5:1 10.00 51 444 43 42 B2 6:1 24.00 43 37 36 35 B2 6:1 24.00 43 37 36 35 B3 6:1 12.66 196 171 167 164 B4 13 13 13 13 13 13 B5 6:1 12.66 196 171 167 164 B4 16.88 322 270 261 256 B10 8:1 16.00 667 561 543 534 B20 10 \$:1 16.00 1054 864 832 815 32:1 48.00 1532 1018 <t< td=""><td>Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [TS] Turns Per [TS] Static Torque [TS] Turns Per Terper Unit Input Torque B1 $anole anole an$</td><td>Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [Ts] Turns Per [Ts] Static Torque [Ts] Turns Per Torque (Ts] Mather Torque RPM Torque RPM Torque RPM Torque RPM A45 RPM A45 RPM A45 RPM A45 RPM A45 RPM A40 B1 5:1 10.00 51 44 43 42 41 40 B2 6:1 20.00 32 26 25 24 23 22 B2 6:1 24.00 43 37 36 35 34 34 B2 6:1 24.00 43 37 36 35 34 34 B3 24:1 96.00 19 14 13 13 12 11 B4 24:1 96.00 196 171 167 164 160 156 24:1 50.66 172 125 117 112 105 98 B20 8:1 16.00 348 <</td><td>Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [TS] Turns Per Incque [TS] Static Torque [TS] Turns Torque Torque (m-lbs) Turns Torque Tor</td><td>Model Number Gear Ratio Turns Pir Inch* Static Torque [[S] Unit Input Torque at Rated Capacity Image: Term Torque Torque Torque Image: Term Various RPMs, term RPM RPM</td><td>Model Number Gear Ratio Turns Pr Inch* (TPI) Static Torque (TS) Static Torque (TS) Unit Input Torque at Rated Capacity <math>T = Runnip Torque (In-lbs) @ Various RPMs (theoretical)** <math>T = Runnip Torque (In-lbs) @ Various RPMs (theoretical)** B1 <math>T = Runnip Torque (In-lbs) @ Various RPMs (theoretical)** RPM <</math></math></math></td></t<>	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [TS] Turns Per [TS] Static Torque [TS] Turns Per Terper Unit Input Torque B1 $anole anole an$	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [Ts] Turns Per [Ts] Static Torque [Ts] Turns Per Torque (Ts] Mather Torque RPM Torque RPM Torque RPM Torque RPM A45 RPM A45 RPM A45 RPM A45 RPM A45 RPM A40 B1 5:1 10.00 51 44 43 42 41 40 B2 6:1 20.00 32 26 25 24 23 22 B2 6:1 24.00 43 37 36 35 34 34 B2 6:1 24.00 43 37 36 35 34 34 B3 24:1 96.00 19 14 13 13 12 11 B4 24:1 96.00 196 171 167 164 160 156 24:1 50.66 172 125 117 112 105 98 B20 8:1 16.00 348 <	Model Number Gear Ratio Turns Per Inch* [TPI] Static Torque [TS] Turns Per Incque [TS] Static Torque [TS] Turns Torque Torque (m-lbs) Turns Torque Tor	Model Number Gear Ratio Turns Pir Inch* Static Torque [[S] Unit Input Torque at Rated Capacity Image: Term Torque Torque Torque Image: Term Various RPMs, term RPM RPM	Model Number Gear Ratio Turns Pr Inch* (TPI) Static Torque (TS) Static Torque (TS) Unit Input Torque at Rated Capacity $T = Runnip Torque (In-lbs) @ Various RPMs (theoretical)** T = Runnip Torque (In-lbs) @ Various RPMs (theoretical)** B1 T = Runnip Torque (In-lbs) @ Various RPMs (theoretical)** RPM <$	

* Of Input Shaft for 1" of Rise

** When calculating running torque, if actual RPMs value is between columns, use column with the lower RPM value.





Duty Limit Service factor (L_2) = Operating time allowed per hour. The numbers greater than 60 are theoretical values and exceed 100% duty, solely to provide base data for adjusting L_2 .

The L_2 values are based on screw jacks loaded at rated capacity, operating in an ambient temperature of 80° F with a maximum allowable temperature rise of 100° F.

For ambient temperatures above 180° F or below -20° F consult UNI-LIFT®. For speeds not shown use the next fastest RPM value.

1. Determine Allowable Duty Cycle Time (D₂)

When the unit load is at rated capacity, and the ambient temperature is at 80° F the L_2 value from the table equals D_2 . If not, proceed to Step 1A.

Step 1A

For different temperature service, or a unit load less than rated capacity, use the following equation to determine the Allowable Duty Cycle Time factor (D_2) .

$$D_2 = [(180 - T_a)*P*L_2]$$

 $T_a =$ Ambient temperature (deg F)

P = Rated capacity (lbs)

L₂ - Duty limit service factor (see Table 8)**

 P_4 = Maximum running load per unit (lbs)

2. Determine if Duty Cycle Time is Acceptable

If $D_2 > = 60$ minutes the application is rated for continuous duty

If $D_2 > = D_1$ than the application is acceptable

If $D_2 < D_1$ than the duty cycle limit has been exceeded for this application. You must do one of the following:

- Reduce the input speed to the screw jack
- Reduce load by adding additional screw jack to the system
- Use a larger size screw jack

If you reduce speed you must recalculate V and $\rm D_1$ from page 73 numbers 4 and 5.

Example:

Consider for a B-10 low ratio 8:1 operating in 70° F ambient temperature, 10,000 pound load, and 1725 RPM, with a rise of 30 inches and 25 cycles per hour.

$$D_{1} = (\frac{2 * \text{Rise} * C_{\text{h}}}{V})$$
$$D_{1} = (\frac{2 * 30 * 25}{102.2})$$

Duty time per hour = 14.7 minutes per hour

$$D_2 = [(180 - 70) * 20,000 * 26]$$

100 * 10,000

Duty cycle limit = 57.2 minutes per hour

Since D_2 is greater than D_1 the application is ok for the duty cycle limit.

TABLE 8

Model Number	Gear Ratio	Turns Per Inch* [TPI]	L ₂ - Duty Limit Service Factor @ Various RPM _s Input Speeds**										
			50 RPM	115 RPM	172 RPM	345 RPM	600 RPM	870 RPM	1140 RPM	1750 RPM	2587 RPM		
R1	5:1	10.00	874	423	302	170	110	82	66	48	34		
ы	10:1	20.00	925	479	363	212	143	111	92	69	52		
B 0	6:1	24.00	1500	723	514	289	186	138	112	81			
DZ	24:1	96.00	458	424	384	301	236	198	172	138			
R5	6:1	12.66	665	320	227	127	81	60	48	34			
80	24:1	50.66	523	328	261	175	127	102	87	68			
B10	8:1	16.88	439	217	156	90	59	44	36	26			
DIU	24:1	50.66	237	171	142	101	76	62	53	41			
B 20	8:1	16.00	327	161	116	66	43	32	26	19			
B20	24:1	48.00	221	145	117	80	59	47	40	31			
B 20	10 2 :1	16.00	306	154	112	65	43	32	26				
630	32:1	48.00	119	105	93	71	54	45	39				
B 50	10 2 :1	16.00	170	88	65	38	25	19	15				
50	32:1	48.00	53	59	54	43	34	28	24				
D75	10 3 :1	10.66	217	110	80	47	30	23					
D/3	32:1	32.00	164	112	91	63	46	37					
B100	12:1	16.00	222	117	87	52	35	26					
DIUU	36:1	48.00	71	84	78	61	48	39					

* Of Input Shaft for 1" of Rise

** When calculating duty limit factor, if actual RPMs value is between columns, use the next higher RPM value.



B-Series, Column Buckle Chart

UNI-LIFT[®]

The maximum estimated screw length (ESL) values in the chart below are based on a **2:1 factor of safety against column buckle**, and on a standard design with a top plate or a rotating design travel nut. Increased load screw lengths are not shown where the slenderness ratio exceeds 400.

- 1. Determine extended screw length (ESL) The ESL is the distance in inches the load screw can extend from the housing. See catalog for the model selected to determine ESL.
- 2. Determine the adjusted screw length (ASL) The chart below is for a standard design top plate or the rotating design travel nut. For other design configurations you must adjust the ESL value using the F factor multiplier to determine the adjusted screw length. ASL = ESL x F
- 3. On the chart below draw a horizontal line to represent the maximum load (P_1).

Using the set of ESL values that apply to your design (guided or unguided), draw a vertical line to represent the ESL or ASL. All of the screw jacks above the point of intersection will be acceptable.



Screw lengths with a column buckle above the dotted line in Chart 2 below (lower than 200) comply with AISC maximum slenderness ratio specified for design and fabrication of

structural steel buildings. This data is for reference only and is not a limiting factor, except as required.

$$\frac{K^*L}{r} <= 200$$

K = Column Factor

L = Extended Screw Length (ESL)

r = Radius of Gyration

See Table on page 73 for r values.

▼ TABLE 9

Design Configuration	F Factor	K Fact (Guided)	tor (Unguided)
Standard Design Top Plate	1	0.65	1.3
Rotating Design Traveling Nut	1	0.65	1.3
Standard Design Clevis End	1.25	0.80	1.6
Keyed Design Top Plate	1.25	0.65	1.3
Keyed Design Clevis End	2	0.65	1.6



▼ CHART 2

Key / Anti-Rotation Options



Key Designed

In applications where rotation cannot be prevented externally, a Keyed Design Screw Jack should be used. These Screw Jacks models are keyed internally to prevent rotation of the screw to produce linear motion.

Key Torque

Key torque is the amount of torque measured in in-lbs that must be overcome to prevent load screw rotation.

Three general methods used to overcome key torque

- 1. Use of external guiding of the load as shown in the illustration below. This method is highly recommended for all applications involving side thrust or column buckle and is mandatory for horizontal applications.
- Configure a system using two or more screw jacks attached to the load. (A rigid structure bolted to more than one UNI-LIFT[®] will not rotate.)
- 3. Using a keyed load screw (keyway full length of Acme Screw). This form of internal guiding is the least preferred method of preventing load screw rotation. Should it become necessary to have a keyed load screw, the load should be no more than 25% of rated capacity in order to minimize key friction problems. Contact UNI-LIFT[®] for assistance in selecting the properly sized keyed UNI-LIFT[®] Screw Jack.

Key torque for all screw jacks models is provided below.



Load Screw Key Torque (output torque at full load)

Capacity (tons)	Unit Key Torque (in-lbs)
1/4	38
3/4 (40 TPI)	98
3/4 (20 TPI)	130
1	196
2	479
3	718
4	1399
5	1756
8	3151
10	4694
15	7705
20	11,411
25	15,375
30	22,587
40	37,006
50	49,421
75	78,142
100	123,947

For reduced loads, key torque is reduced proportionately. Multiply table values by load proportion factor.

 $f = \frac{\text{Actual Load (lbs)}}{\text{Rated Capacity (lbs)}}$

Rotation Prevention

Rotation of Load Screw or Traveling Nut must be prevented in order to produce travel (linear motion).



Guide Sizing

Guides must be sized to prevent bending or deflection and aligned in true position with the Screw Jack and the Load Screw. If more then

one unit is attached to a common structure, the tendency to rotate is resisted by reaction in the structure, instead of the guides.



WARNING! Keyed Rated Capacity

For keyed applications where operating loads are expected to exceed 25% of rated capacity, contact UNI-LIFT[®] for technical assistance.







- $\mathbf{A} = Width of flat$
- \mathbf{B} = Length of flat
- \mathbf{C} = End of clevis to certer line of pin hole
- \mathbf{D} = Diameter of pin hole
- E = Diameter of clevis end
- **F** = Diameter of clevis end (Tube End)
- $\mathbf{G} = \text{Closed height pin to pin}$
- **J** = Extended height pin-to-pin
- **K** = Height of UNI-LIFT housing
- L = Length from pin hole (tube end) to housing
- \mathbf{M} = Length from pin hole (tube end) to input shaft

Model Number*	Α	В	С	D	E	F	G	J	К	L	М
	(in)	(in)	(in)	(in)	(in)						
B2	.75	1.50	.75	41	1.00	1.38	9.25 + Travel	G + Travel	6.31	1.18 + Travel	3.25 + Travel
B5	1.00	2.00	1.00	.66	1.50	2.13	13.62 + Travel	G + Travel	9.04	2.06 + Travel	4.75 + Travel
B10	1.25	2.50	1.25	.78	1.75	2.50	14.79 + Travel	G + Travel	9.19	2.34 + Travel	5.16 + Travel
M2	0.75	1.50	0.75	0.41	1.00	1.38	7.38 + Travel	G + Travel	4.44	1.18 + Travel	3.25 + Travel
M3	0.75	1.50	0.75	0.41	1.00	1.38	7.00 + Travel	G + Travel	4.06	1.18 + Travel	3.25 + Travel
M4	1.00	2.00	1.00	0.66	1.50	2.13	9.75 + Travel	G + Travel	5.18	2.06 + Travel	5.00 + Travel
M5	1.00	2.00	1.00	0.66	1.50	2.13	10.06 + Travel	G + Travel	5.50	2.06 + Travel	4.75 + Travel
M8	1.25	2.50	1.25	0.78	1.75	2.50	12.56 + Travel	G + Travel	6.43	2.34 + Travel	5.66 + Travel
M10	1.25	2.50	1.25	0.78	1.75	2.50	11.41 + Travel	G + Travel	5.68	2.34 + Travel	5.16 + Travel
M15	1.50	2.50	1.25	0.91	2.25	2.50	12.91 + Travel	G + Travel	6.81	2.34 + Travel	5.66 + Travel
M20	1.75	2.75	1.38	1.03	2.50	3.13	17.2 + Travel	G + Travel	7.56	2.69 + Travel	6.63 + Travel

V DIMENSIONAL CHART

*Double Clevis option limited to model shown above.

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Double Clevis Column Buckle



The Pin-to-Pin values in the Chart 3 are based on a 2:1 factor of safety against column buckle, on a Double Clevis Screw Jack.

Increased load screw lengths are not shown where the slenderness ratio exceeds 400.

- 1. Determine maximum extended height pin-to-pin (J) The maximum extended height is the distance between the clevis pins, in the fully extended position. Refer to page 78.
- 2. Determine the maximum unit load: (P₁, lbs.) On multi-unit systems where load is not equally distributed, change P₁ to the greatest load supported by one unit.

 $\begin{array}{cc} \mathsf{P}_{_1} = \mathsf{P}_{_2} & \mathsf{P}_{_2} = \text{Total system load} \\ \hline \mathsf{N} & \mathsf{N} = \text{Number of screw jacks} \end{array}$

3. Select correct size screw jack

On the chart below draw a horizontal line to represent the maximum load $[P_1]$. Draw a vertical line to represent the maximum extended height [J]. All of the screw jacks below the point of intersection will be acceptable.



Contact UNI-LIFT!

Contact UNI-LIFT for advice and technical assistance in the layout of your ideal UNI-LIFT System.

CONTACT INFORMATION:

Customer Service: (630) 408-9349 Toll Free: (888) 984-1924 sales@uniliftjacks.com

▼ CHART 3



UNI-LIFT[®] 79





Lift a 30,000 pound Turbine Engine 20 inches in 90 seconds. Lifting will occur three times per hour, once a month, inside a clean factory.

A lifting frame secures the engine and positions the screw jacks so the load is equally distributed. Linear slides handle side loads and a hard stop is part of the frame.

The lifting frame will place the center of the screw jack load screws on a 10 foot square. 460 Volt 3-phase power is available, preference for a standard 1750 RPM motor. The illustration shows an Upright Translating Design with a Top Plate.

They are looking for a complete lift system.

Determine the part numbers for these items:



2 Motor

3 Gear Reducer

4 Mitre Gear Box

5 Shafting

1 Mechanical Screw Jack

Determine UNI-LIFT Screw Jack Model

See steps 1-7 on page 68 for detailed explanations.

1. Determine the maximum load on one screw jack (P₁ lbs) The load is equally distributed.

$$P_1 = \frac{P_2}{N} = \frac{30,000}{4} = 7,500 \text{ lbs}$$

2. Select the screw jack size

Per the drawing, the screw jacks will be in compression, follow the additional steps 1-3 on page 71.

• No additional allowances are needed for boots and for other miscellaneous clearances.

Travel = 20 inches = ESL ASL = ESL x F = 20 x 1 = 20 inches

- The load is guided, placing this information on chart 1, page 71, shows screw jacks with a capacity of 4 tons and higher are acceptable. This is not a high cycle application, so 100% of crated capacity will be used. To minimize cost the lowest tonnage is selected as a starting point, this is the **M4**.
- Determine desired load screw velocity (V_din/min) One way travel under load is 20 inches in 1.5 minutes

$$V_{d} = \frac{\text{Rise}}{t_{2}} = \frac{20}{1.5} = 13.33 \text{ in/min}$$



4. Determine desired input speed: (RPM,)

M4 has three different ratios, start with the low ratio, this will generally yield the lowest shaft speed.

TPI = Turns of the input shaft for 1 inch of rise RPM_d = TPI x V_d = 16 x 13.33 = 213 RPM

5. Determine actual load screw velocity (Vin/min)

The 7.5 to 1 reducer gives us the closest desired input speed.

Input Speed =
$$\frac{1750}{7.5}$$
 = 233 RPM

$$V = \frac{RPM}{TPI} = \frac{233}{16} = 14.58 \text{ in/min}$$

The desired velocity (V_{d}) is 13.33, this should be acceptable.

6. Calculate the required duty cycle time (D, in/min)

In absence of other information, the average ambient temperature inside a factory is assumed to be 80 degrees.

$$D_{1} = \frac{(2 \times \text{Travel x } C_{h})}{V} = \frac{(2 \times 20 \times 3)}{14.58} = 8.23 \text{ min/hour}$$
$$D_{2} = \frac{(\{180-T_{a}\} \times P \times L_{2})}{100 \times P_{2}} = \frac{(\{180-80\} \times 8000 \times 23)}{100 \times 7500} = 24.53 \text{ min/hour}$$

 $\rm D_{1} < \, D_{2},$ the M4 low ratio in this application is with in acceptable duty cycle limits

Screw Jack Model Number is M4UT0200LT

Application Example



2 Motor

Determine Motor

See steps 1-7 on page 69 for detailed explanations.

1. Determine unit running load proportion factor (f)

Check with customer, unless told otherwise, assume ${\rm P_2} = {\rm P_3}$

$$f = \frac{P_3}{(P \times N)} = \frac{30,000}{(8000 \times 4)} = 0.94$$

2. Determine unit running torque (T_1 , in-lbs)

$$T_1 = (T \times f) + To = (202 \times 0.94) + 5 = 195 \text{ in-lbs}$$

3. Determine system running torque (T₂, in-lbs)

See page 66, question #11, for arrangement efficiency (e,)

$$T_2 = (T_1 \times N) = (195 \times 4) = 975 \text{ in-lbs}$$

4. Determine system power, (System hp)

See page 66, question #11, for reducer efficiency (e_)

hp =
$$\frac{(T_2 \times \text{RPM}_s)}{63025 \times e_2} = \frac{(975 \times 233)}{(63025 \times 0.9)} = 4.01 \text{ hp}$$

5. Determine system starting torque (Ts₂, in-lbs)

 $T_{S2} = \frac{([\{T_s \times f\} + To] \times N)}{e_2} = \frac{([\{342 \times .094\} + 5] \times 4)}{0.9} = 1,451 \text{ in-lbs}$

6. Determine motor starting torque (T_{sm}, in-lbs)

$$T_{sm} = \frac{T_{s2}}{(R \times e_2)} = \frac{1451}{(7.5 \times 0.9)}$$
 215 in-lbs

7. Determine motor running torque ($T_{\rm rm}$, in-lbs)

$$T_{m} = \frac{T_{s_2}}{(R \times e_1)} = \frac{975}{(7.5 \times 0.8)} = 163 \text{ in-lbs}$$

8. Select the Motor

See page 49 for motor specifications, select motor with values that are = > the calculated hp, $\rm T_{sm},$ and $\rm T_{rm}$

UM17 - 5 hp 1750 RPM 3 Phase 184TC Frame

3 Gear Reducer

See pages 52 and 53 for product details.

1. Determine system running torque $(T_2, in-lbs)$

See page 66, question #11, for arrangement efficiency (e_1) The reducer must drive all 4 screw jacks.

$$T_2 = \frac{(T_1 \times N)}{e_1} = \frac{(195 \times 4)}{0.8} = 975 \text{ in-lbs}$$

2. Select the Gear Reducer

See page 53 for gear reducer specifications, select gear reducer with output torque => system running torque T_2 and match the selected motor frame size.

UGRD2 - Size C Gear 7.5 to 1 ratio

4 Mitre Gear Box

See pages 54 and 55 for product details.

1. Determine mitre gear box torque (T_m in-lbs)

Each mitre box must drive 2 screw jacks

$$T_m = T_1 \times N = 195 \times 2 = 390$$
 in-lb

2. Select the Mitre Box

See page 54 for mitre box specifications, select mitre box with input hp, output torque, and maximum input RPM = > actual motor hp, calculated mitre box T_m , and actual gear reducer output RPM

UMG5 – Size 5 Mitre Box





Application Example

UNI-LIFT®

5 Shafting

See pages 49, 52 - 54, and 58 for product details. Create drawing of the system layout to help determine shaft dimensions.

1. Determine Shaft Size

Select shaft size with maximum torque rating = > actual motor starting torque (T_{sm}) x ratio.

 T_{sm} actual x ratio = (436 x 7.5) = 3270 in-lbs.

Shaft Size 4 maximum torque rating of 3540 in-lbs (page 58)

For ease of installation, use the same size shafting for all positions.

2. Determine Shaft Model Number for Shaft ER and FR

The layout is symmetrical, both shafts will be the same.

Calculate shaft to shaft distance on drawing

60 - 5.26 - 5.72 - 2.26 = 46.80 in.

Indentify Gear Reducer shaft diameter = 1.25 in. Indentify Mitre Box shaft diameter = 1.00 in. Use Shaft Matrix Chart on page 58 to determine model number

US4B0468FH, quantity 2x

3. Determine Shaft Model Number for Shaft AE, BE, CF, and DF

The layout is symmetrical, all 4 shafts will be the same. Calculate shaft to shaft distance on drawing

60 - 4.18 - 5.09 = 50.73 in.

Indentify Screw Jack shaft diameter = 0.75 in. Indentify Mitre Box shaft diameter = 1.00 in Use Shaft Matrix Chart on page 58 to determine model number

US4B0507DF, quantity 4x









UNI-LIFT screw jacks have set a new standard for linear motion control. Improving on the time-tested concept of converting rotary movement into linear motion, the UNI-LIFT series is ideal for a variety of industrial lifting and handling applications.



Machine Screw Jacks



Ball Screw Jacks



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UNI-LIFT[®] Application Ideas

UNI-LIFT®



Marine

100-Ton UNI-LIFT Screw Jacks help keep the ferry dock running

Engineers utilized two (2) UNI-LIFT 100-ton Screw Jacks with 15' of travel to raise and lower the ramp on each ferry dock along the Mississippi River, USA. The Department of Transportation engineers needed a way of lifting and lowering ramps during high and low tide conditions, while holding up to the harsh environmental conditions of the Gulf Coast.



Aircraft Maintenance

Aircraft docking systems need the flexibility and precision of UNI-LIFT Screw Jacks

UNI-LIFT Screw Jacks are used for scheduled aircraft maintenance overhauls. Engineers at this repair station decided that UNI-LIFT Screw Jacks were the perfect choice to position and adjust the complex scaffolding that was set up around the aircraft. Their precision movement and flexibility has proven to be an asset in getting the job done efficiently and safely.

Material Handling

UNI-LIFT are used in many different material handling applications

UNI-LIFT Screw Jacks are used extensively in a variety of material handling applications. Whether used to position conveyer belts, place tension on overhead beams or to move heavy-duty equipment, UNI-LIFT Screw Jacks are the ideal solution for many jacking, tensioning, and positioning applications. Whether you have one or multiple lifting points, UNI-LIFT Screw Jacks are the perfect solution for many different OEM material handling applications.







Fabrication

UNI-LIFT positions sections of segmental bridge forms

Fabricators use UNI-LIFT 10-Ton Screw Jacks to position fabricated sections of forms used in precast segmental bridge sections. UNI-LIFT Screw Jacks were used due to the harsh environmental location of the casting facility. The engineers were also able to operate the Screw Jacks from an overhead centralized location so that each section came together as needed. This process saves time in the form setup making the job run more efficiently than previous methods.





Motion Control

UNI-LIFT are key to a variety of motion control applications

When controlled motion is required, many design engineers in virtually every industry around the world use UNI-LIFT Mechanical and Ball Screw Jacks for their precision, power and performance. UNI-LIFT accessories provide flexibility and expandability in heavy-duty motion control solutions.

Manufacturing

5-ton Double Clevis Screw Jacks keep the doors of these plating tanks running smoothly

When engineers needed a quick and compact way of opening the large doors of these plating tanks, they selected a UNI-LIFT solution. The application utilizes two 5-ton double-clevis Screw Jacks, with a motor and a limit switch box mounted on each. The operator just pushes a button to open the doors and pushes another to close them. This method greatly enhances operator safety and helps prevent crosscontamination between tanks.







▼ Complete the following information to select the right products:

NOTE: This Worksheet is available for print on-line at: www.uniliftjacks.com

Name:		Title			
Company:		Address:			
City:		State:		ZIP:	
Phone:	Fax:	Email	:		
Total System Load:		Is the Load Equally Dis	tributed:	Yes	_ No
If No, what is the Maxin	num Load On One Sc	rew Jack:			
No. of Screw Jacks in S	System:	Travel Requ	ired:		
Travel Speed Required	/Min:	Linear Speed Require	ments: Min.	Ма	x
Is the Load Guided? Ye	es	No			
No Side Thrust Force is	Allowed on Screw (A	Application with side thrust force requir	es external guiding	g of load)	
Load Condition:					
Compressed	Tension	Both			
Mounting Style:					
Upright	Inverted	Double Clevis			
Screw Configuration: (*	Keyed Screw Jacks are to be	used at 25% of rated capacity)			
Translating	Rotating	*Keyed		_ Anti-Backlas	sh
Operating Cycles: Per H	Hour Ho	urs/Day	Days/Week		
Drive:					
Manual	Electric	Air		Hydraulic	
Power Available:					
Voltage	Phase	Cycle (Hz)			
Environmental: (Check	all that apply)				
Wet Oil C	orrosive Dirt	Dust Vibration	Explosion F	Proof Shoo	ck/Impact
Amhient Temperature:	(Specify Bange)				
	(opcony hange)				
Ball Screw Application:	l				
Brake Stopping Distar	nce (in)	Life Expectancy			
Accessories Required:	(Check all that apply)				
Top Plate	_ Clevis End	_ Motor Adaptor	Stop Nut	Limit S	witch
Bellows Boots	_ Encoder	_ Hand Wheels	Couplings	Reduce	ers
Mitre Gear Boxes	Shafts	_ Custom Controls			





Numerically choose the arrangement that best illustrates your application. Other configurations are available upon request.



NOTE: This Worksheet is available for print on-line at: www.uniliftjacks.com

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Email: sales@uniliftjacks.com Online: www.uniliftjacks.com



Product Overview



UNI-LIFT[®] Offers Other Linear Actuation Products Including...



MACHINE SCREW JACKS

...to suit your application

- 1/4 ton to 250 ton capacities
- Maximum travel (up to) 232 inches
- Maximum speeds (up to) 129 in/min.
- · Variety of mounting options

Precision rolled acme threads allow positioning within thousandths of an inch.



BALL SCREW JACKS

...the most complete in the industry

- 1 ton to 100 ton capacity
- Maximum travel (up to) 230 inches
- Maximum speeds (up to) 175 in/min.
- Ideal for high speeds and continuous duty applications

Precision screw lead offers exact positioning for multiple actuator systems.



JACK SYSTEM ACCESSORIES

... for single-or multi-actuator systems

- Hand Wheels
- Electrical Controls
- Rotary Limit Switches
- Couplers
- Motors
- Motor Adapters

 - Worn Gear Reducers
 - Screw End Adapters
 - Boots
 - Shafts

Safety, Installation and Maintenance



Note: Unless specified in the sales order, the services of a field engineer are not included with the purchase of UNI-LIFTJacks and related equipment. Installation, maintenance and safety instructions must be given to all personnel directly responsible for the installation, maintenance and operation of the UNI-LIFT equipment.

General Guidelines and Installation

The customer is responsible for ensuring that there are no destructive conditions which could affect the UNI-LIFT Jack(s) or complementing equipment. Conditions that may be considered destructive include, but are not limited to:

- 1. Excessive input speeds
- 2. Extreme shock loading
- 3. Mechanical or thermal overloading
- 4. Exceeding recommended duty cycles
- 5. Side loading of the load screw

Each UNI-LIFT Jack in the system must be specified in accordance with the stated requirements and precautions contained in this Catalog. All calculations and specifications must be reviewed and approved by the customer's application design engineer in advance of installation.

Be certain that:

- The rated capacity of the UNI-LIFT Jack exceeds the maximum load that may be applied to it during use.
- The maximum allowable input shaft speed (RPM_a) of the UNI-LIFT Jack will not be exceeded.



NOTE: For maximum input speeds and other UNI-LIFT specifications, refer to the Motor Sizing Charts on pages 69 and 74 in this section for your Jack.

The foundation for the UNI-LIFT Jack is sufficiently rigid to maintain correct alignment with connected machinery and that it has sufficient strength to support the maximum load.

- The foundation has a flat mounting surface to assure uniform support for the UNI-LIFT Jack. Be sure the opening in the foundation for the protective tube or the load screw is as small as possible, so that the unit is supported over the greatest possible area.
- The method of preventing load screw rotation (so that translation will occur) is sufficiently strong. Refer to the Load Screw Key Torque on page 77 for complete details.

Lubrication Procedure

New UNI-LIFT Jacks are shipped with grease in the housing. Lubrication is recommended at regular intervals. Such intervals are determined by the duty cycles of the Jack, but should be performed a minimum of once every 60 days.

Please see the instruction sheet that accompany your UNI-LIFT product for more information.



WARNING !

Never perform any maintenance, lubrication adjustment or repair procedures on a UNI-LIFT Jack or any associated

transmission equipment until you are absolutely certain that the prime mover cannot be remotely or automatically started. Always lockout power before beginning procedures. Make sure the load is properly supported before the UNI-LIFT brake or other holding devices are removed.



Lubricant Requirements

The lubricant should not be corrosive to gears or to ball or roller bearings and must be neutral in reaction. In addition,

the lubricant must be oxidation resistant and must be non-channeling. Operating temperatures must be considered when selecting lubricants. UNI-LIFT recommends the following extreme pressure greases or their equivalents.

- 1. For operation up to 180° F [82° C]: Use lithium based grease, it should have a viscosity of 840 to 890 SUS at 100° F, and 76 to 84 SUS at 210° F.
- 2. For operation up to 400° F [204° C]: Use DuBois MPG-2 Grease, NLGI Grade 2. If another brand of high temperature grease is used, it should have a viscosity of 539 SUS @100° F.
- 3. For operation down to -100° F [-73° C]: Use Shell Aero Shell Grease 7 (Low temperature aviation synthetic hydrocarbon microgel grease).

Note: Standard UNI-LIFT models are designed to operate at 80° F [27° C] with a 100° F temperature rise. For higher temperatures, special seals are required. Contact UNI-LIFT for additional information.

Special Requirements



USDA approved grease for food industry applications and special grease for extremely low temperature applications

below -100° F [-73° C] is available. Contact UNI-LIFT for additional information.







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Machine Screw Jacks Page 12-33



Ball Screw Jacks Page 34-46



Screw Jack Accessories Page 47-63



FAQ & More Technical Information Page 64-89

CONTACT INFORMATION:

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